

**FREE**

Webinar Series #1



Magister Terapan PENS

# Robotics



**Dr. Ir. Endra Pitowarno, M.Eng**  
Recent Topics on Robotics Vehicle and  
Its Applications

**Ir. Dadet Pramadihanto, M.Eng, Ph.D**  
Robot in Cyber Physical Systems



**Dr. Ir. Son Kuswadi**  
Disaster Robotics

**Dr. Eng. Indra Adji Sulistijono, ST, M.Eng**  
Robotics - From Competition Towards  
Its Applications



**Moderator:**  
**Dr. Eng. Bima Sena Bayu**  
**Dewantara, S.ST, MT**

**Waktu Pelaksanaan:**  
Senin, 24 Agustus 2020  
Pukul 13.00 - 16.00 WIB

**Link Registrasi:**  
[bit.ly/webinarPascaPENS#1](http://bit.ly/webinarPascaPENS#1)



**Fasilitas e-certificate**  
\*Pastikan telah melakukan registrasi

Terbuka untuk umum



**Contact Person:**  
**Puspa - 081230008675**



# Robotics - From Competition Towards Its Application



**Dr.Eng. Indra Adji Sulistijono**

Politeknik Elektronika Negeri Surabaya (PENS)  
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Mobile: +62 817 330 282  
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# Dr.Eng. Indra Adji Sulistijono, ST, M.Eng.

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- Dosen di Program Studi D4 Teknik Mekatronika dan Program Pascasarjana Terapan S2 Teknik Elektro, **Politeknik Elektronika Negeri Surabaya (PENS)**.
- SDN Endrakila, SMPN 1 dan SMAN 2 Madiun
- S1 – Jurusan Teknik Mesin – **Institut Teknologi Sepuluh Nopember Surabaya, Indonesia**
- S2 – Dept. of Human and Artificial Intelligent Systems – **University of Fukui, Japan.**  
Bidang kajian: **visual control**.
- S3 – Dept. of Human Mechatronics System – **Tokyo Metropolitan University, Japan.**  
Bidang kajian: **robot vision (Robotika)**.

## Research Topic

- Intelligent Mechatronics, Computational Intelligence
- Visual Control, Robot Vision, Industrial Automation
- Robot for Disable, Disaster, and Agriculture
- Scopus H-Index: **6**, GoogleScholar H-Index: **9**
- Journal Paper: **12**; Int'l Conf: **55+3**; Nat. Conf: **29**

## Expert (Mobile Robotics)

- WorldSkills Competition 2009, 2011, 2013, 2015, 2017, (2019)
- ASEAN Skills Competition 2014, 2016, (2018), (2020)
- Juri LKS Nasional 2010 – 2017, 2020.





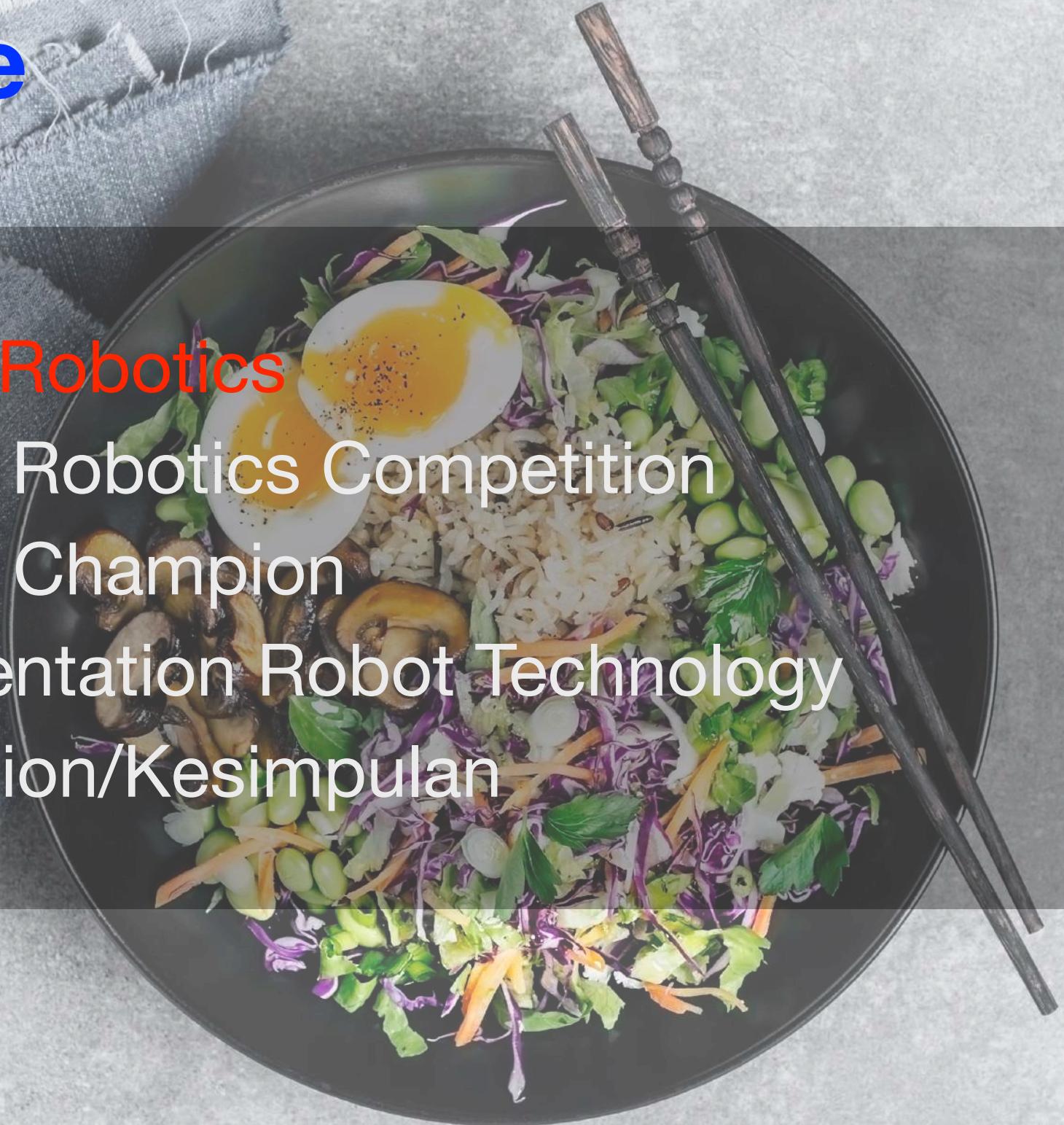
# Outline

- What is Robotics
  - (Mobile) Robotics Competition
  - Road to Champion
  - Implementation Robot Technology
  - Conclusion/Kesimpulan
- 



# Outline

- What is Robotics
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# Dr.Eng. Indra Adji Sulistijono

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Websites: [www.pens.ac.id](http://www.pens.ac.id)

**Intelligent Mechatronics and  
Industrial Automation Lab.**

Human Mechatronics Systems  
Research Group (HuMeX)

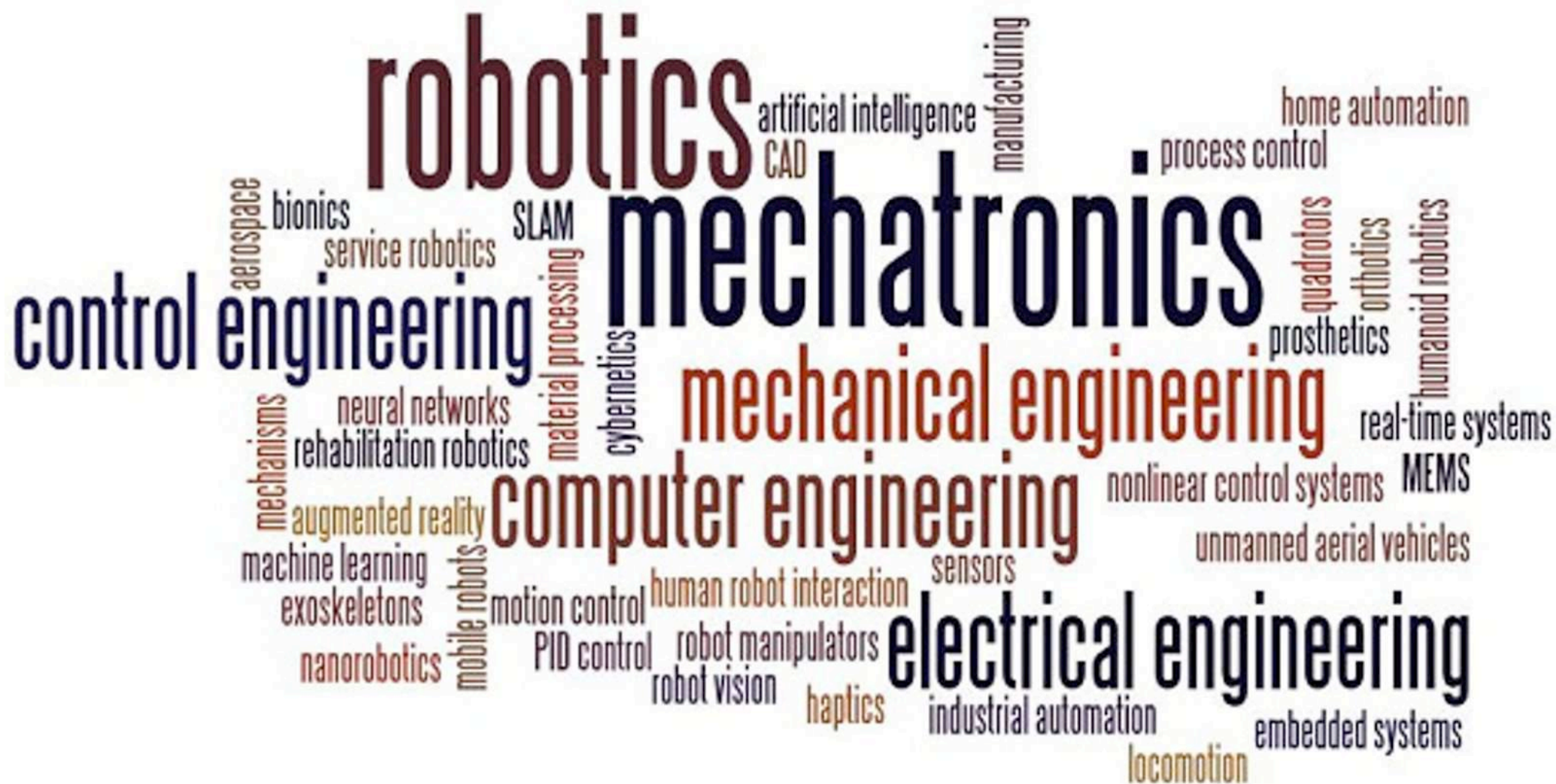
**Training Center for Mobile  
Robotics**

Gedung Pascasarjana Terapan  
Lantai 3





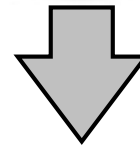
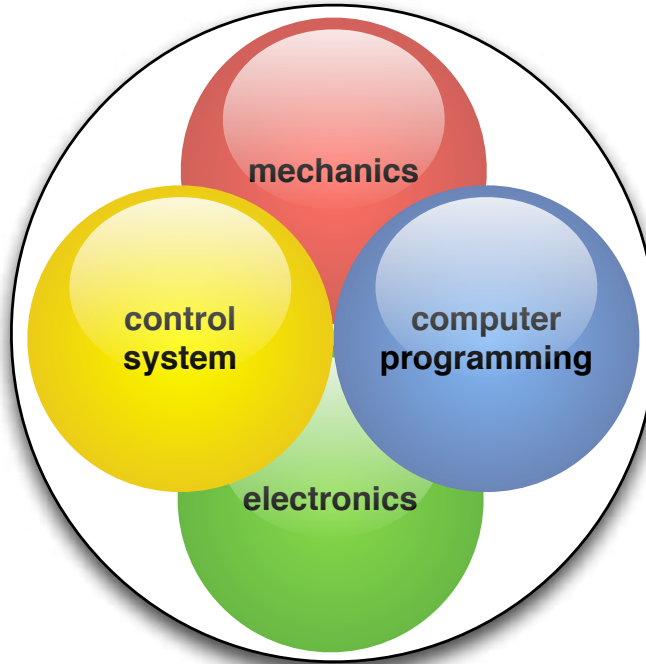
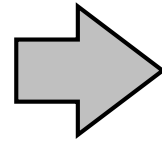
# What is Robotics?



Referensi: <https://www.google.com>

# What is Mobile Robotics?

**MOBILE  
ROBOTICS**



Designing, building, and maintaining robots to solve problems in industries from manufacturing to aerospace, mining to medicine

**Mobile  
Management  
System**

**Mobile  
Robotics**

**Object  
Management  
Systems**



# Mobile Robotics

## Dari Kompetisi Menuju Implementasi

**Tujuan Kompetisi:** Mendesain, membuat dan merakit, memprogram, mengoperasikan dan melakukan pengujian robot yang dapat bergerak dari tempat start ke tempat tujuan yang telah ditetapkan serta menyelesaikan tugas yang telah ditentukan sebelumnya secara tuntas.

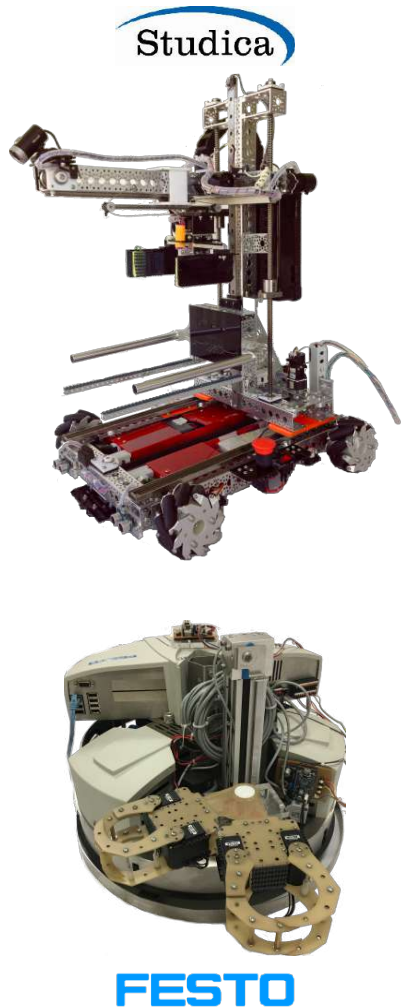
Teknisi/engineer robotika yang bekerja di industri, laboratorium atau office tertentu, mereka merancang, menjaga, mengembangkan aplikasi baru dan melakukan penelitian untuk memperluas potensi robot. Peran robot dimulai pada masalah industri tertentu, di sektor tertentu.

Misalnya, dalam manufaktur, mungkin ada kebutuhan untuk meningkatkan kapasitas dengan membuat robot untuk tugas yang dapat diotomatisasi. Mobile robot juga dapat dirancang untuk menjelajahi area yang tidak dapat diakses atau berbahaya bagi manusia.

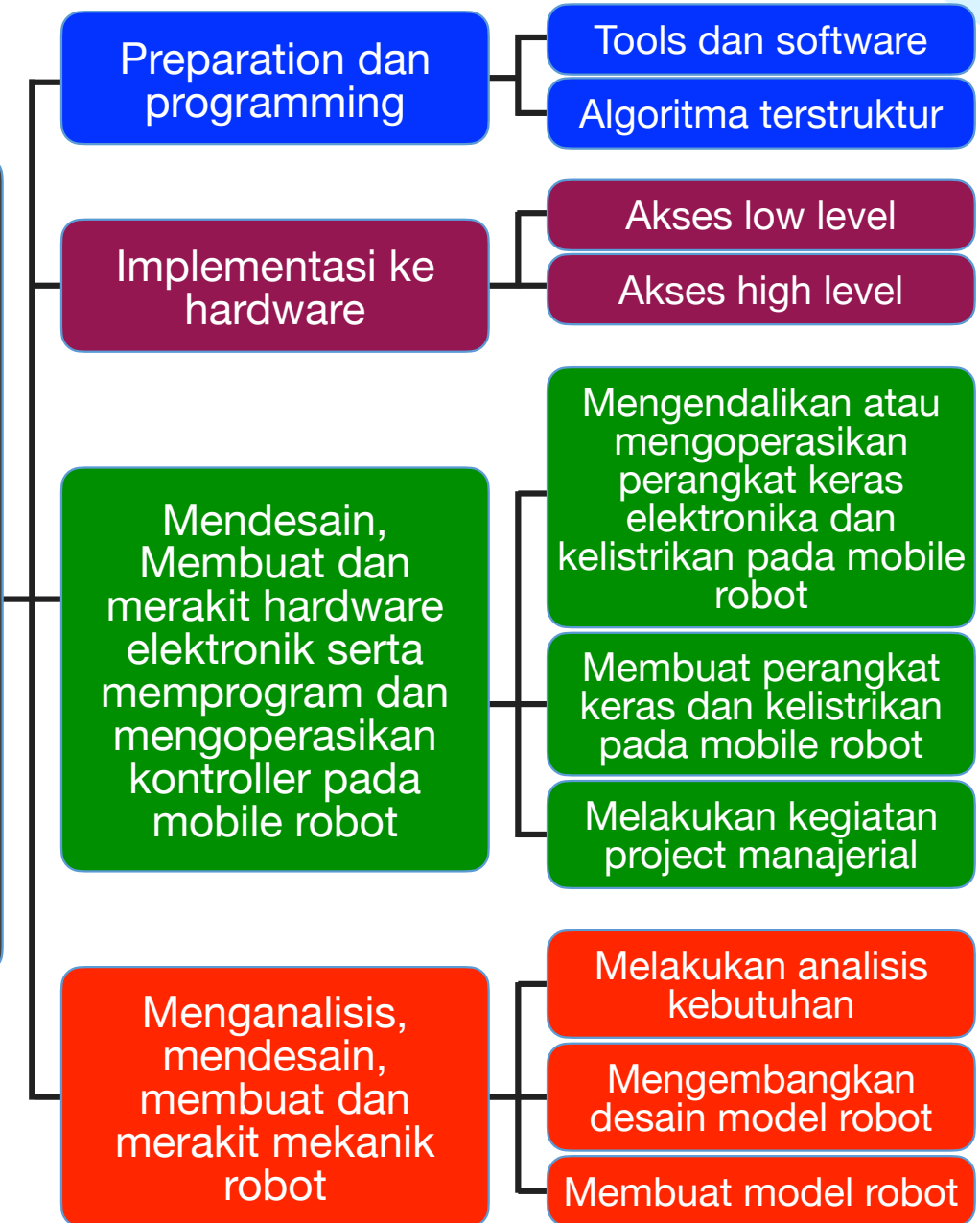
Mobile robotics adalah bagian penting dari industri, dengan aplikasi di berbagai sektor, termasuk manufaktur, pertanian, aerospace, pertambangan, kedokteran dan lain-lain.



# Pemetaan Standar Kompetensi Mobile Robotics



Mendesain, membuat dan merakit, memprogram, mengoperasikan dan melakukan pengujian robot yang dapat bergerak dari tempat start ke tempat tujuan yang telah ditetapkan serta menyelesaikan tugas yang telah ditentukan sebelumnya secara tuntas



Tujuan Utama

Fungsi Kunci

Fungsi Utama



# World Framework/Platform



**FESTO**

## World Skills Competition

- WSC 2007 Toyohashi, Japan
- WSC 2009 Calgary, Canada
- WSC 2011 London, UK
- WSC 2013 Leipzig, Germany

## ASEAN Skills Competition

- ASC 2014 Hanoi, Vietnam
- ASC 2016 Kuala Lumpur, Malaysia
- ASC 2018 Bangkok, Thailand



**Studica**

## World Skills Competition

- WSC 2015 Sao Paulo, Brasil
- WSC 2017 Abu Dhabi, UAE
- WSC 2019 Kazan, Russia
- WSC 2021 Shanghai, China

## ASEAN Skills Competition

- ASC 2020 Singapore  
(postpone to April 2021)



# Prepare Before You Go

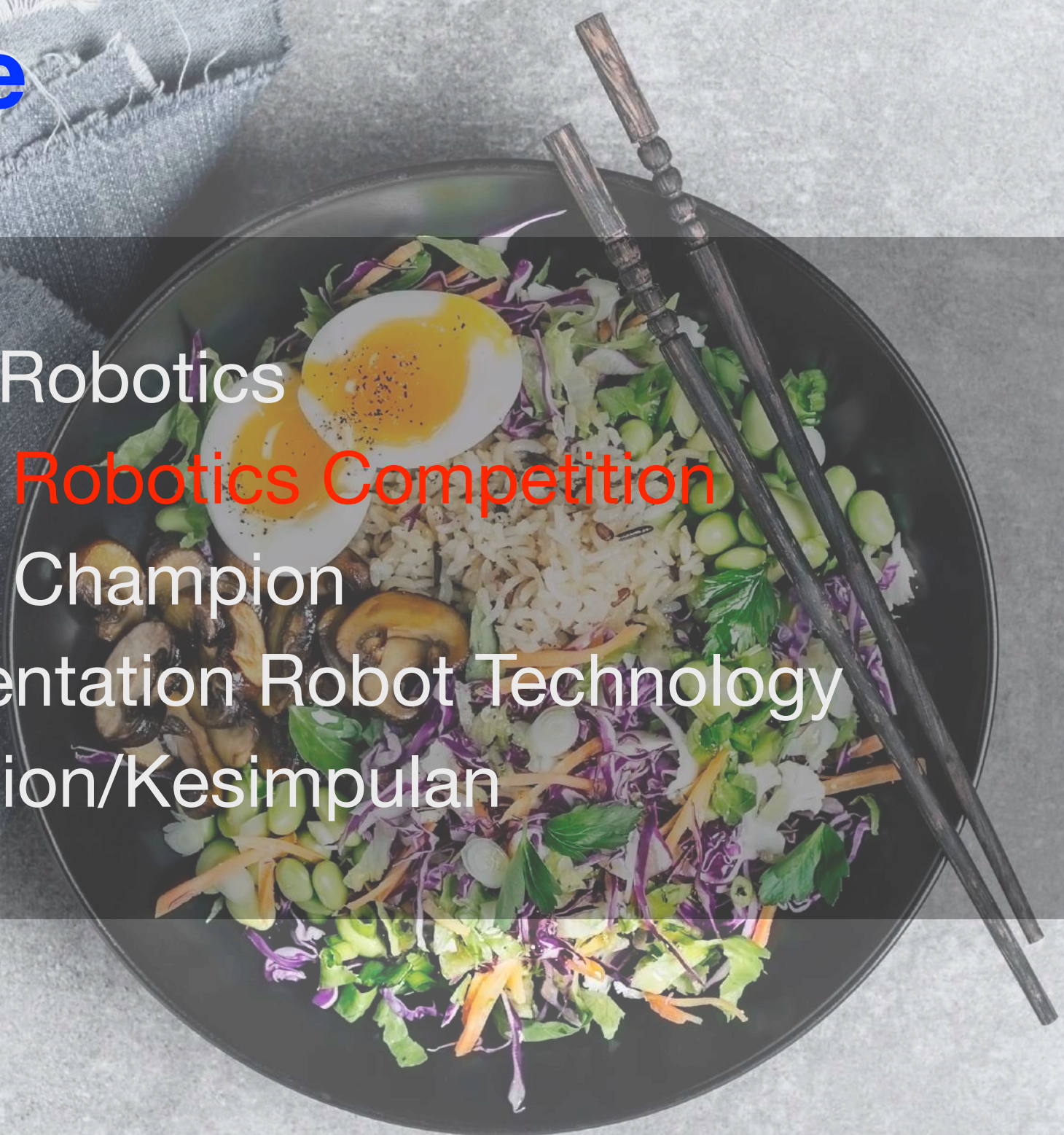
- CPU:
  - NI myRIO from National Instruments (NI)
  - LabVIEW software
- Sensor:
  - 3 infrared
  - 2 ultrasonic
  - 1 QTI (line sensor)
  - 1 gyro sensor
- Actuator:
  - 4 motor DC + driver
  - 4 motor + driver
  - Indicator Lamps
- Frame
- Displacement gear





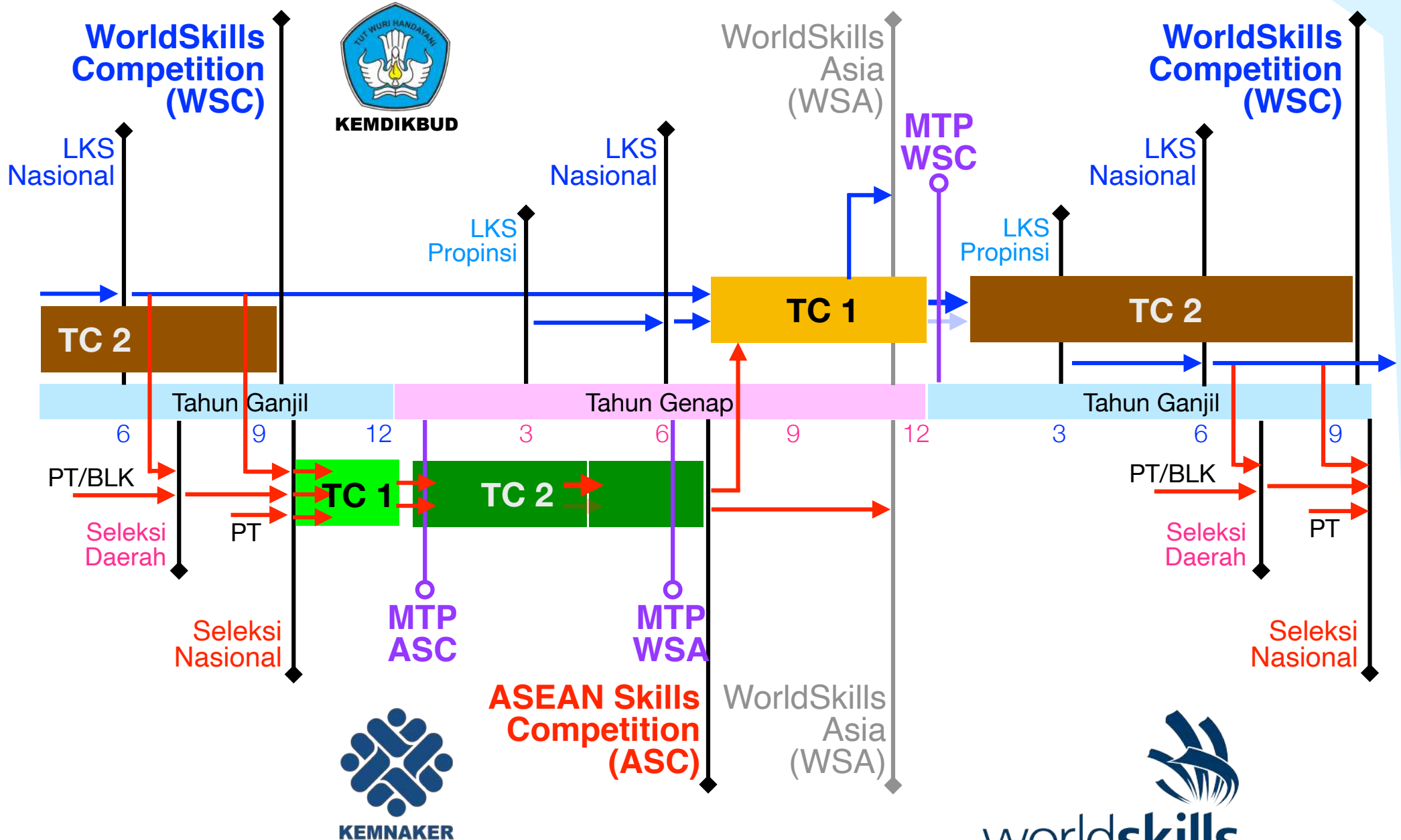
# Outline

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- (Mobile) Robotics Competition
- Road to Champion
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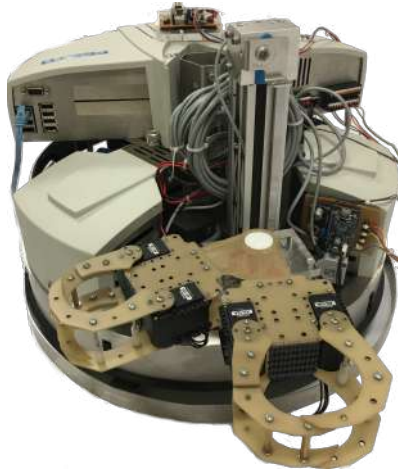
# Kalender WorldSkills Indonesia





# Mobile Robotics

ASC 2016

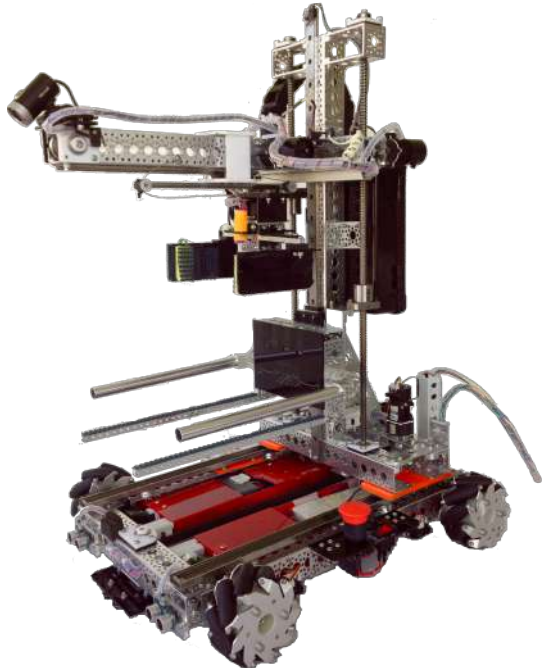


ASC 2018



ASC 2020

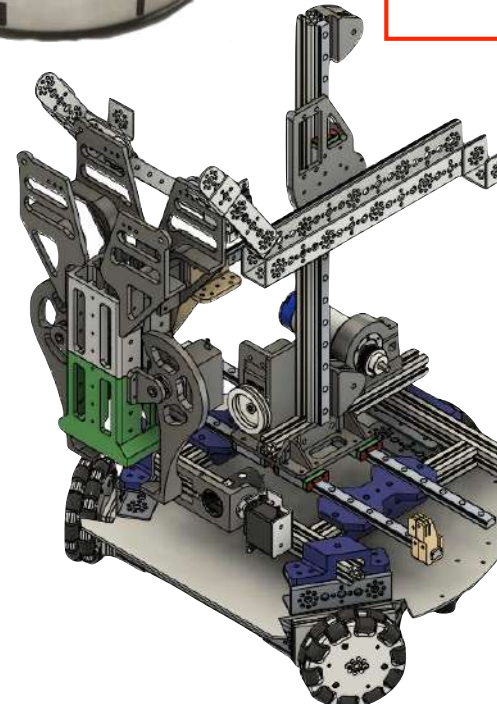
*Postpone to  
April 2021*



WSC 2015



WSC 2017














WSC 2019

September  
2021

WSC 2021



# Prestasi Mobile Robotics Indonesia

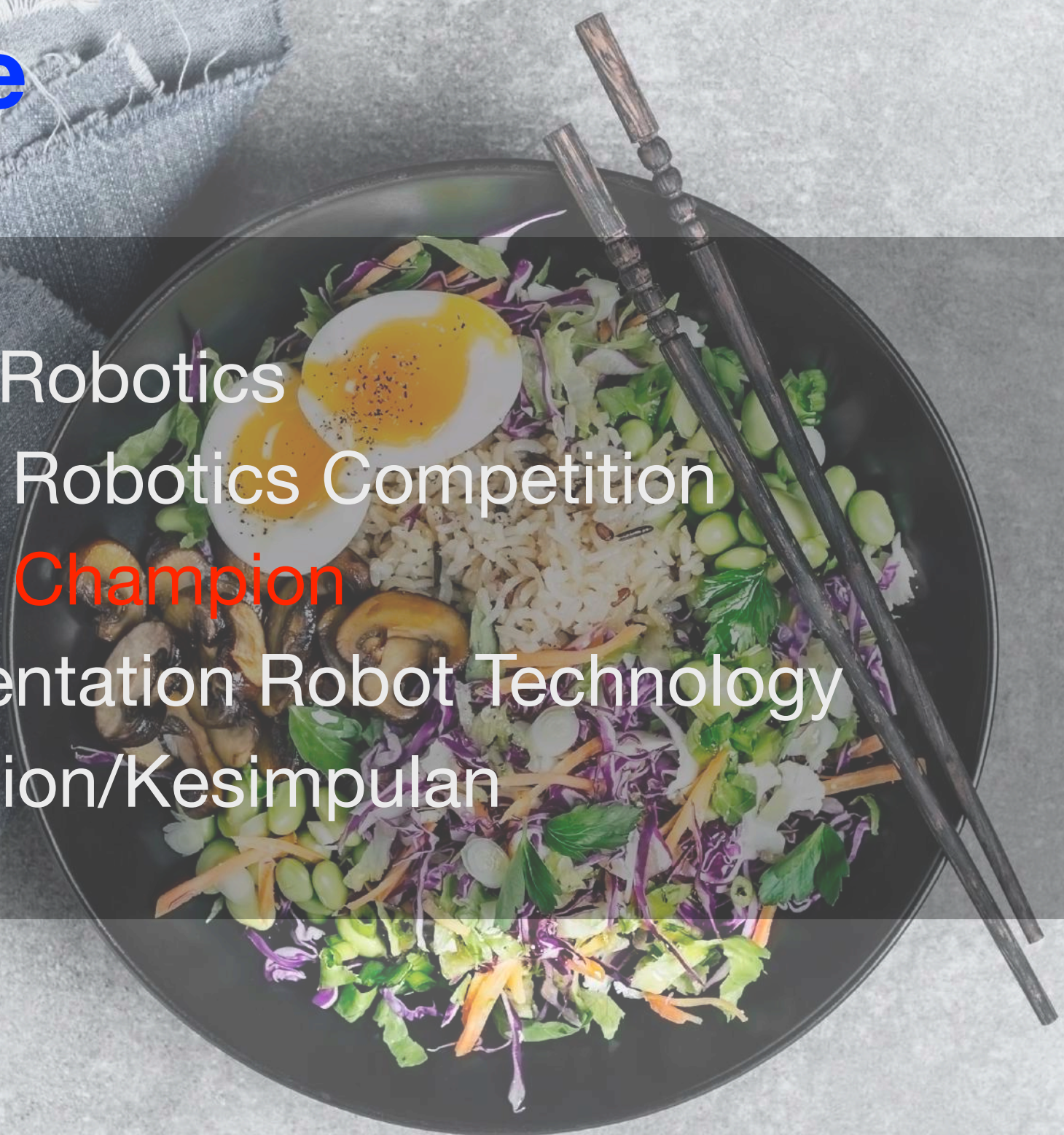
Tahun	Kompetisi	Nama Competitor	Nilai	Peringkat/Prestasi
2009	WSC 2009 Calgary, Canada	 A. Arif Gunawan Amri Ivan Afandi	489 (600)	10 besar dari 14 negara
2010				
2011	WSC 2011 London, United Kingdom	 Muhammad Tawakkal Deni Setiawan	539 (600)	<b>Bronze Medal</b>
2012				
2013	WSC 2013 Leipzig, Germany	 Kevin Wincharso Muh. Luthfi Musrah	499 (600)	12 besar dari 19 negara
2014	ASC 2014 Hanoi, Vietnam	 Alfin Junaedy Teguh Satrio Wibowo		<b>Gold Medal</b>
2015	WSC 2015 Sao Paulo, Brasil	 Hendriana Helda Pratama Lutfi Nur Indrawan	538 (600)	<b>Medal of Excellence &amp; Best of Nation</b>
2016	ASC 2016 Kuala Lumpur, Malaysia	 Andy Yuniawan Eko Mustofa		<b>Gold Medal</b>
2017	WSC 2017 Abu Dhabi, Uni Arab Emirate	 Andy Yuniawan Eko Mustofa	709 (800)	<b>Medal of Excellence</b>
2018	ASC 2018 Bangkok, Thailand	 Moch. Rifki Ramadhani Muhammad Rois		<b>Bronze Medal</b>
2019	WSC 2019 Kazan, Russia	 Wahyu Arga Pratama Muh. Rizqi Pratama	690 (800)	16 besar dari 24 negara
2020	ASC 2020 Singapore (postpone April 6-11, 2021)			
2021	WSC 2021 Shanghai, China			





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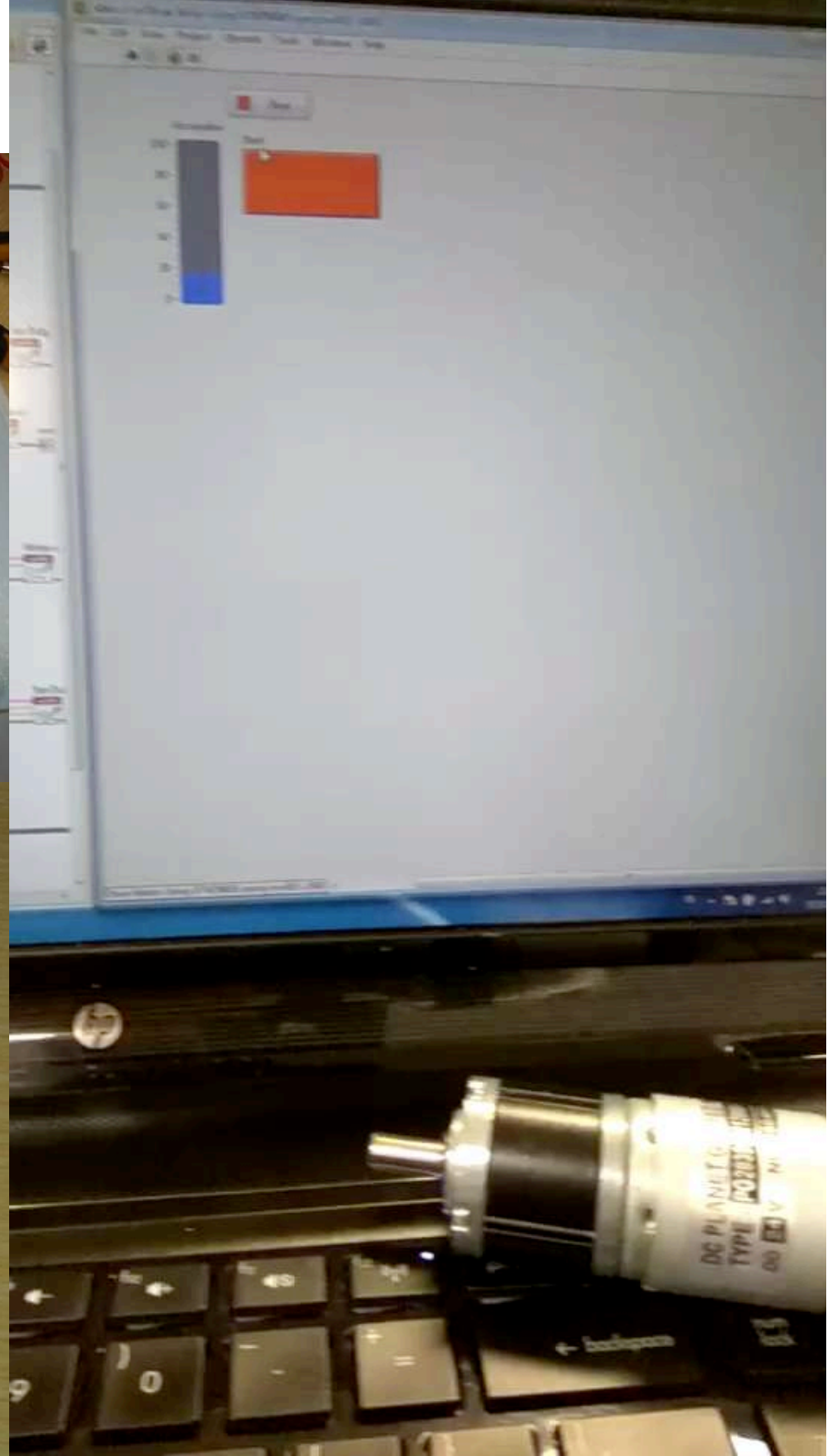


# LabView & myRIO Camp





# LabView & myRIO Camp



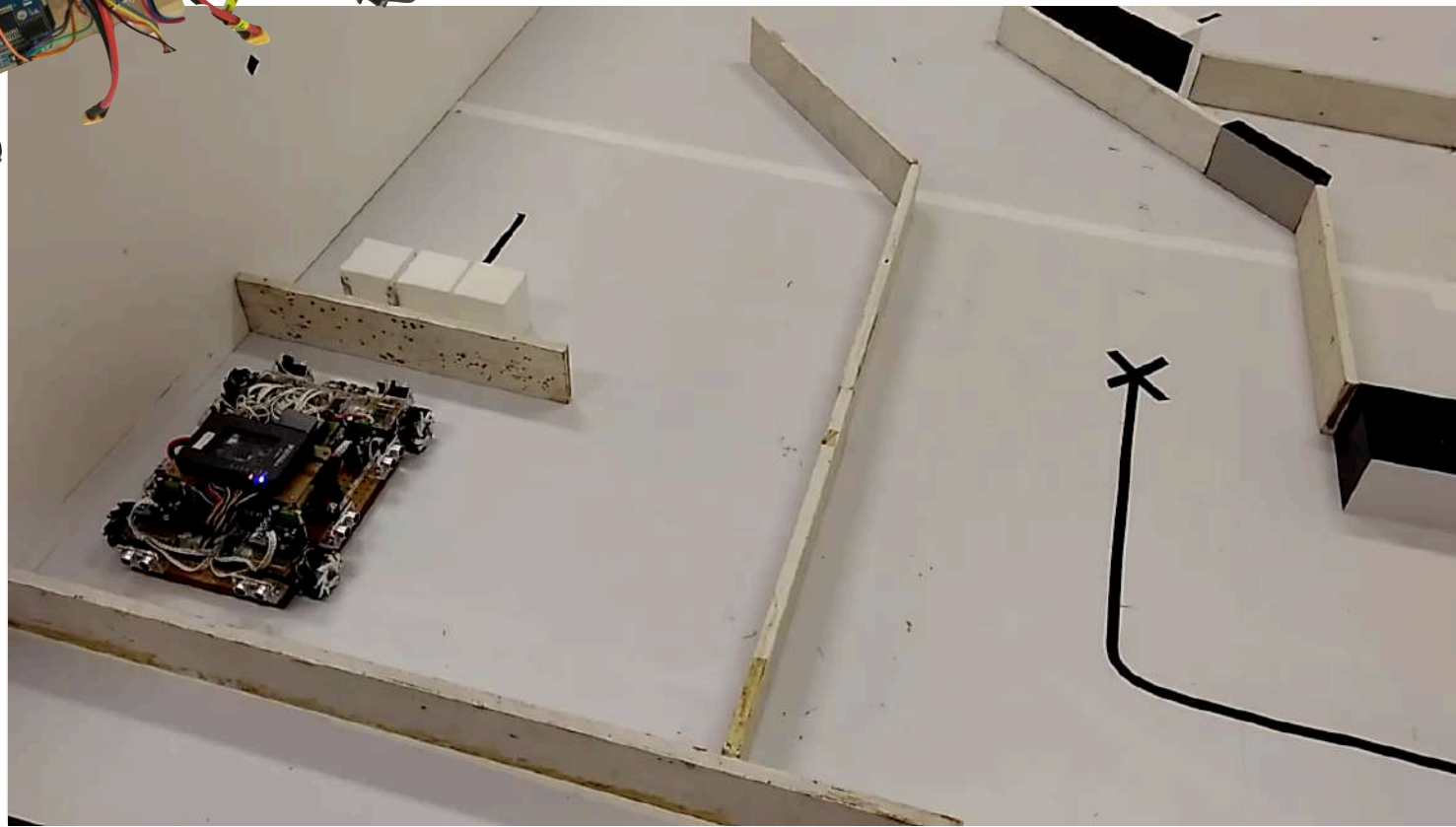
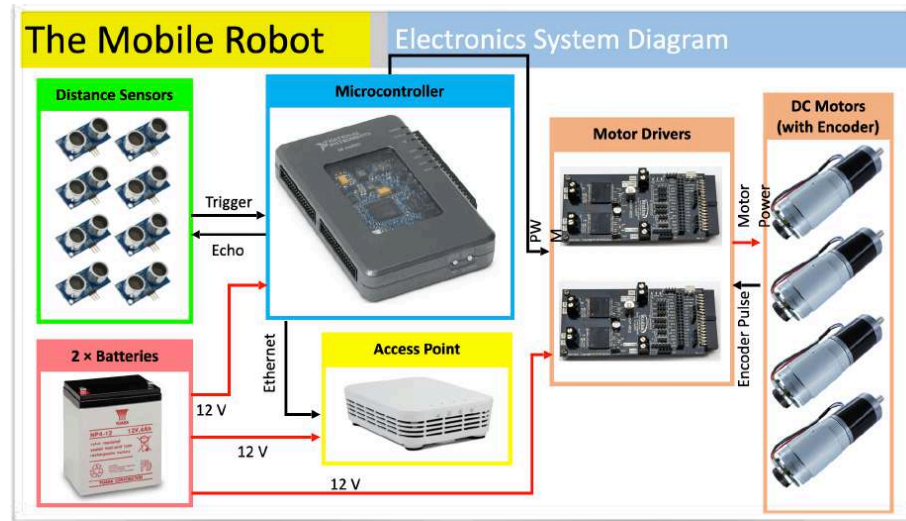
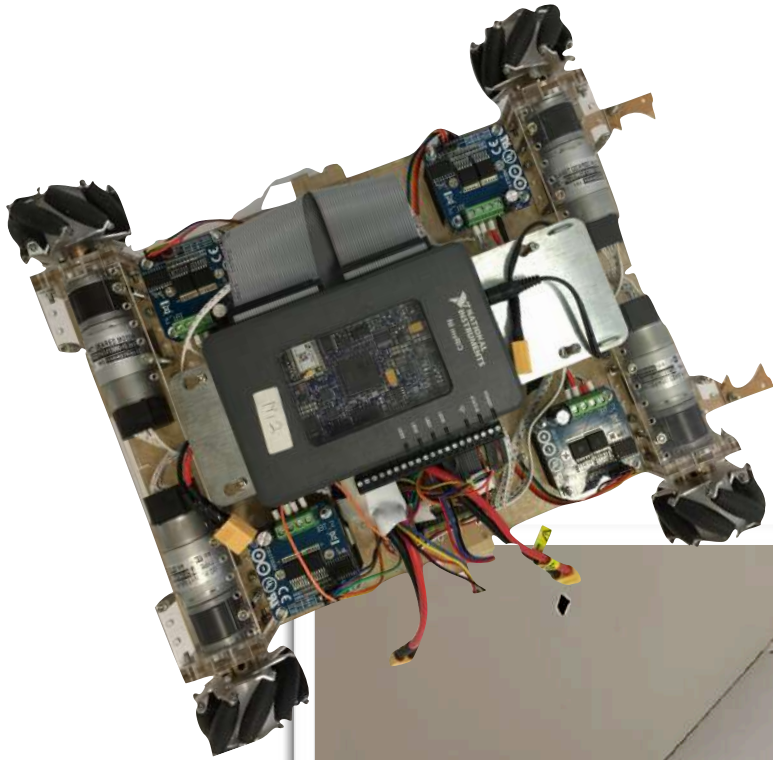


# Assembly Robot





# Try Out, Try Out ... & Try Out





# MTP - Materi Test Project

Biasanya dikeluarkan oleh WSSS enam bulan menjelang kompetisi

**CIS Marking**

## Test Project



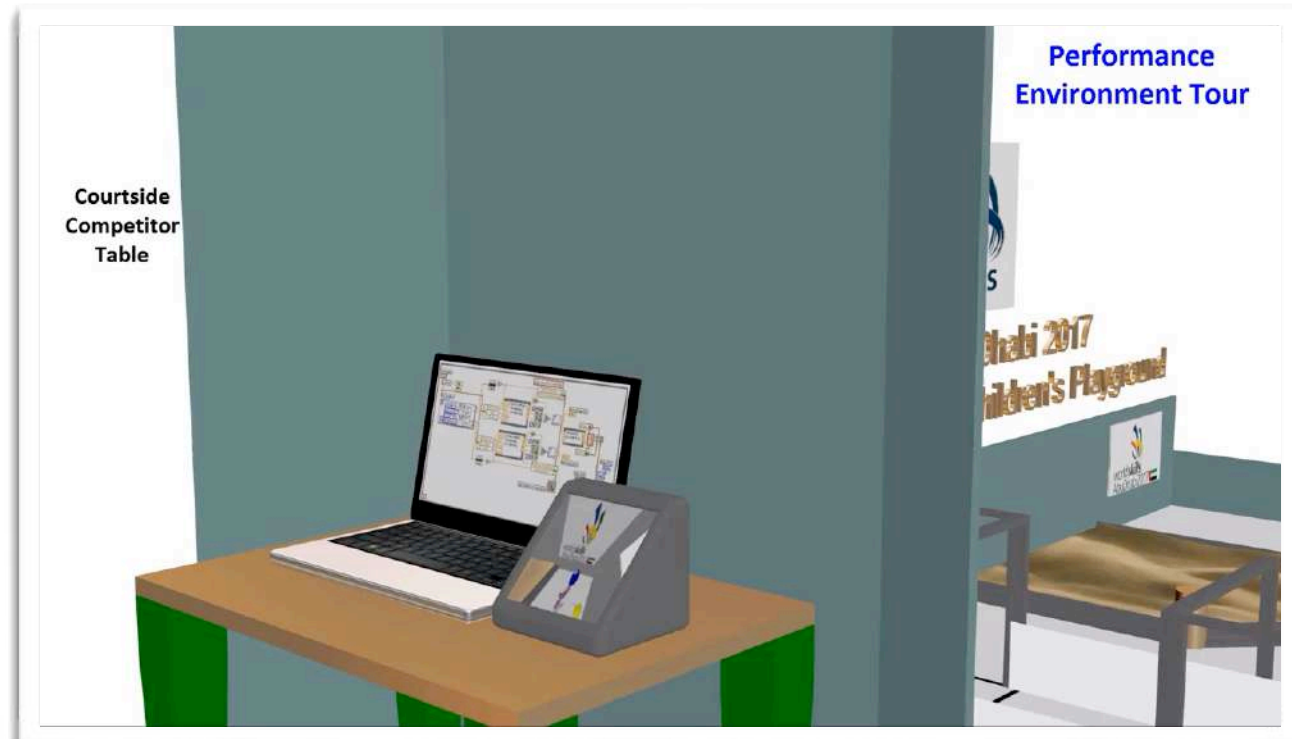
**TEST PROJECT  
MOBILE  
ROBOTICS**  
Playground Monitor Robot  
WSC2017\_TP23\_actual



Submitted by:  
Name: Bob Tone  
External Test Project Designer

WSC2017\_TP23\_actual

	Skill name	
	<b>Mobile Robotics</b>	
	Criteria	Mark
A	Work Organization & Management	10,00
B	Communication and Interpersonal skills	10,00
C	Design	25,00
D	Fabrication & Assembly	5,00
E	Core Programming, Testing & Adjustment	20,00
F	Performance Review and Commission	30,00



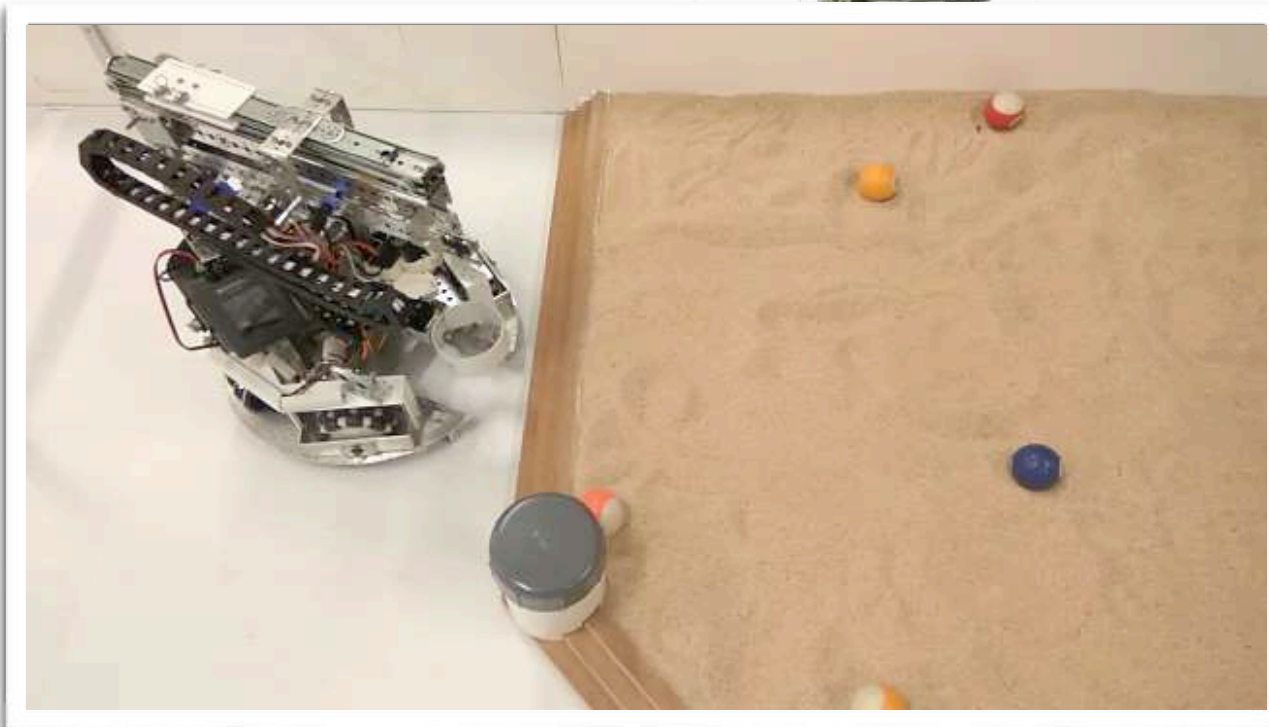
**Video**



# Output Product Training Center



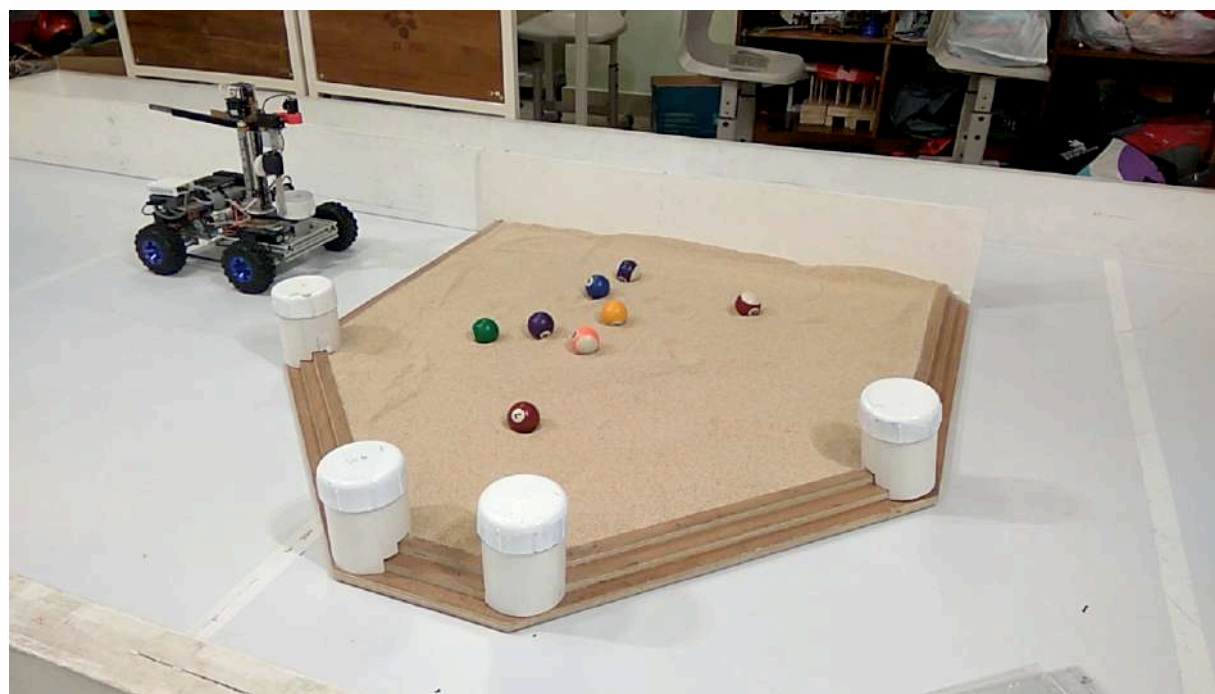
Journal (Report)  
dan Robot



- \* Frame/Structural
- \* Mobility Management
- \* Object Management
- \* Wiring
- \* Computer Programming
- \* Additional Cost



# Output Product Training Center

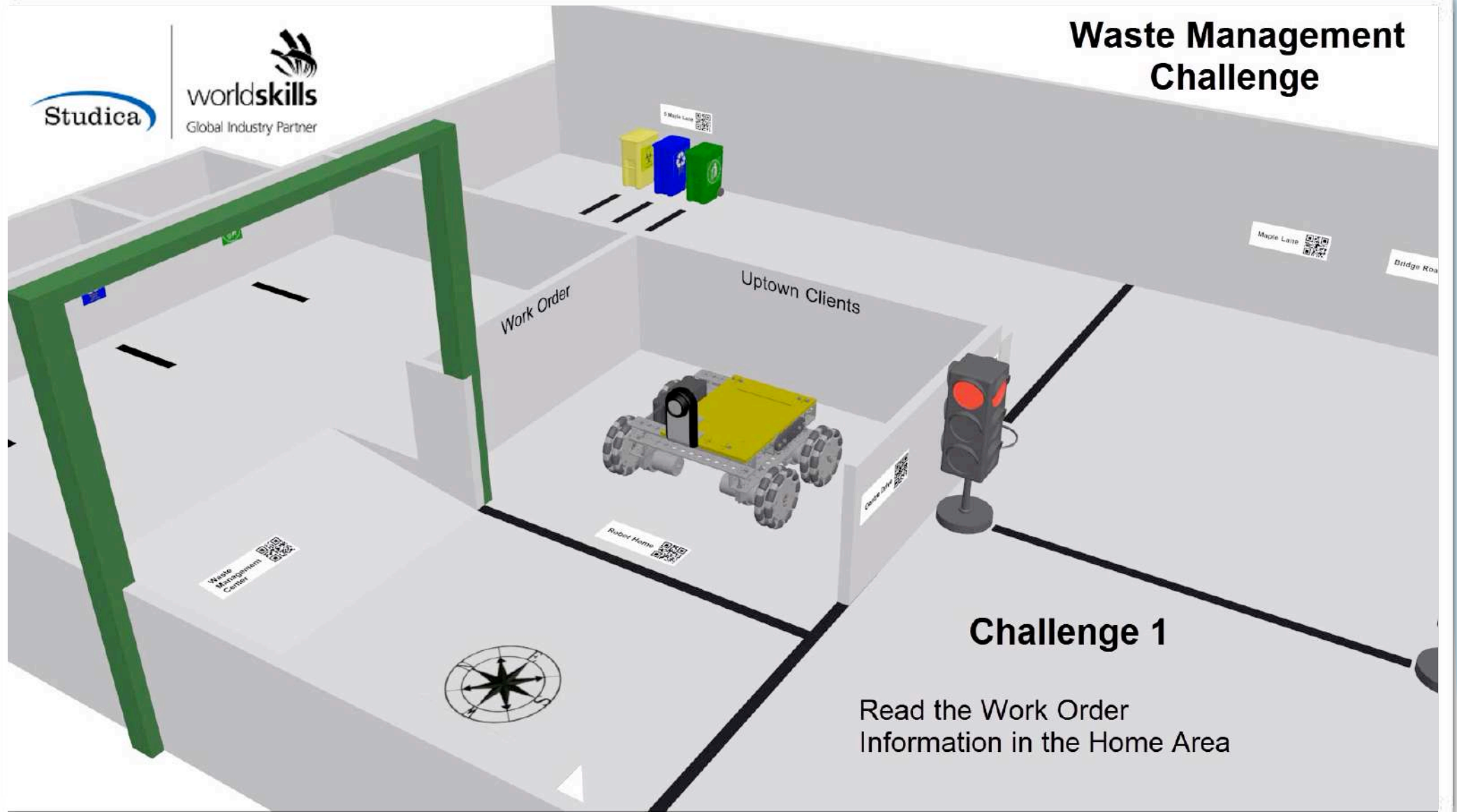




# Next Challenge ASC-WSA



## Waste Management Challenge





Penghargaan Dalam 5 Tahun Terakhir (dari pemerintah, asosiasi, atau institusi lainnya)

# AWARDS

No.	Judul Penghargaan	Institusi Pemberi Penghargaan	Tahun
1.	Finalis Indonesian ICT Awards 2013 (Peran: Dosen Pembimbing)	Kemenkominfo Jakarta, Indonesia	2013
2.	Finalis PIMNAS 2013 (Peran: Dosen Pendamping)	Dikti, Kemendiknas Mataram, Indonesia	2013
3.	Tanda Kehormatan "SATYALANCANA KARYA SATYA XX TAHUN"	Presiden Republik Indonesia	2013
4.	Semifinalis Microsoft IMAGINE CUP (Peran: Dosen Pembimbing)	Microsoft Indonesia, Jakarta	2014
5.	Gold Medal untuk Bidang Kejuruan Mobile Robotics (Peran: Expert dan Dosen Pembimbing)	ASEAN Skills Competition 2014 Hanoi, Vietnam	2014
6.	Medal for Excellence Bidang Kejuruan Mobile Robotics (Peran: Expert dan Dosen Pembimbing)	WorldSkills Competition 2015 Sao Paulo, Brazil	2015
7.	Best of Nation Bidang Kejuruan Mobile Robotics (Peran: Expert dan Dosen Pembimbing)	WorldSkills Competition 2015 Sao Paulo, Brazil	2015
8.	Medali Perunggu Presentasi Kategori PKM- KC3 PIMNAS 2015 (Peran: Dosen Pendamping)	Belmawa, Kemristekdikti Kendari, Indonesia	2015
9.	Juara 1 Seleksi Nasional untuk Bidang Kejuruan Mobile Robotics (Peran: Expert dan Dosen Pembimbing)	Dirjen Bina Latas, Kemnaker Bekasi, Indonesia	2015
10.	Finalis PIMNAS 2016 (Peran: Dosen Pendamping)	Belmawa, Kemristekdikti Bogor, Indonesia	2016
11.	Best Paper Award pada the 2 <sup>nd</sup> International Conference on Soft Computing and Data Mining	Bandung, Indonesia	2016
12.	Gold Medal untuk Bidang Kejuruan Mobile Robotics (Peran: Expert dan Dosen Pembimbing)	ASEAN Skills Competition 2016 Kuala Lumpur, Malaysia	2016
13.	Finalis PIMNAS 2017 (Peran: Dosen Pendamping)	Belmawa, Kemristekdikti Makassar, Indonesia	2017
14.	Juara 1 Seleksi Nasional untuk Bidang Kejuruan Mobile Robotics (Peran: Expert)	Dirjen Bina Latas, Kemnaker Bekasi, Indonesia	2017
15.	Medallion for Excellence untuk Bidang Kejuruan Mobile Robotics (Peran: Expert)	WorldSkills Competition 2017 Abu Dhabi, Uni Emirat Arab	2017
16.	Dosen Berprestasi Mata Kuliah Berbasis Teori Di Program Studi Teknik Mekatronika Semester Gasal 2017/2018	Politeknik Elektronika Negeri Surabaya (PENS)	2018
17.	Finalis PIMNAS 2018 (Peran: Dosen Pendamping)	Belmawa, Kemristekdikti Yogyakarta, Indonesia	2018
18.	Bronze Medal untuk Bidang Kejuruan Mobile Robotics (Peran: CoExpert dan Dosen Pembimbing)	ASEAN Skills Competition 2018 Kuala Lumpur, Malaysia	2018
19.	Finalis PIMNAS 2019 (Peran: Dosen Pendamping)	Belmawa, Kemristekdikti Denpasar, Indonesia	2019



# AWARDS





# Outline

- What is Robotics
- (Mobile) Robotics Competition
- Road to Champion
- **Implementation Robot Technology**
- Conclusion/Kesimpulan



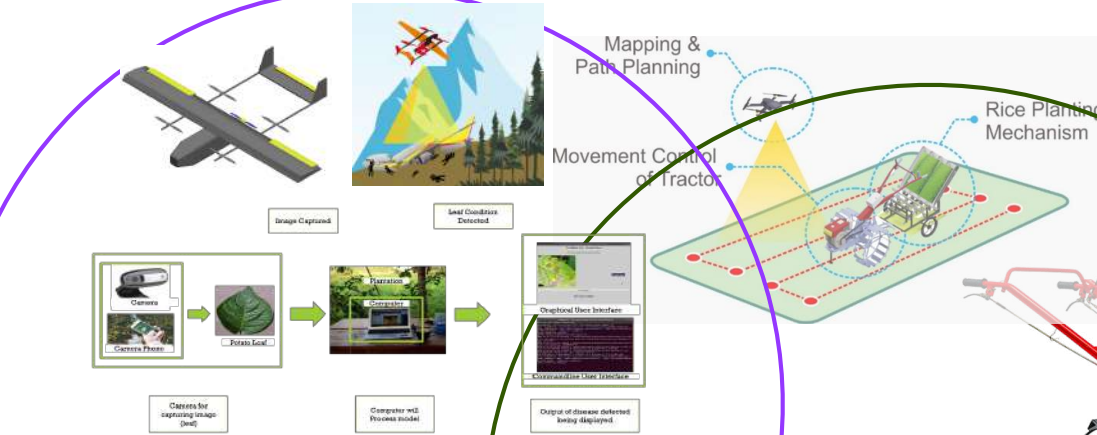


# Implementation Robot

Mahasiswa D4: <60  
 Mahasiswa S2 Terpan: 6  
 Scopus H-Index: 6  
 GoogleScholar H-Index: 9  
 Journal Paper: 12  
 International Conference: 55+3  
 National Conference: 29  
 Pengalaman Pendanaan: 8

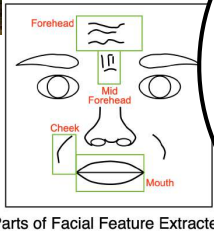
## Vision Robot

Muhammad Khoiril  
 Muhammad Ilham P.  
 Alif Habib H.  
 M. Nazhat Adiba  
 Agus Prayudi  
 ...



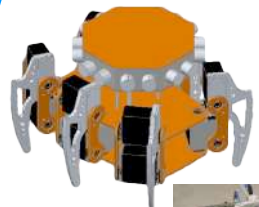
## Agriculture Robot

**Nobby Bagus M. (S2)**  
 Moch Rifki Ramadhani  
 Alfian Rahmansyah  
 Rizqi Amaliatus S  
 ...



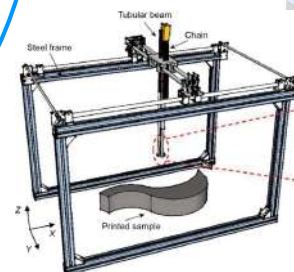
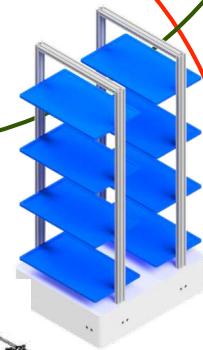
## Partner Robot

**M. Dwijotomo (S2)**  
**Marianus Bayu Aji K. (S2)**  
**Teguh Satrio Wibowo (S2)**  
**Alfin Junaedy (S2)**  
 Rokhmat Febrianto  
 ...

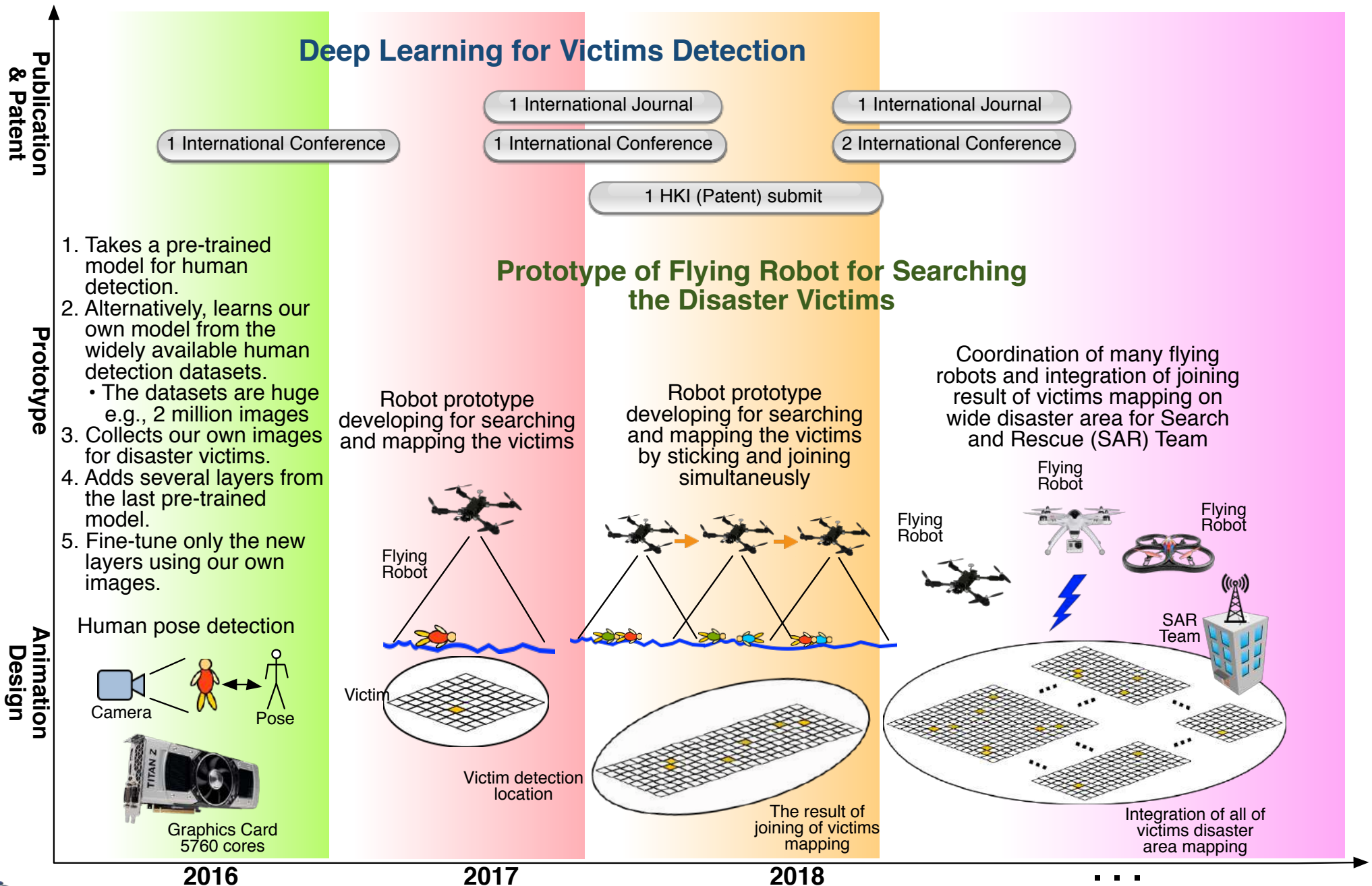


## Robot for Hospital, Building

**Rodik Wahyu Indrawan (S2)**  
**Andy Yuniawan (S2)**  
 Muhammad Rois  
 M. Khoiril Abdulloh  
 ...



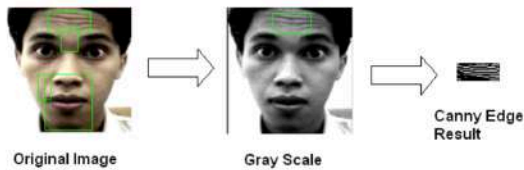
# Roadmap (Vision Robot) → HuMeX



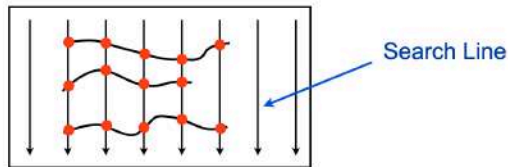


# Facial Expression Recognition

## Forehead

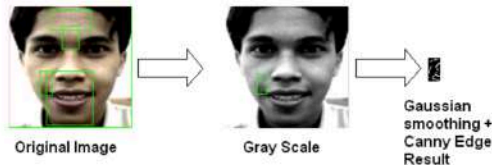


The procedures of counting the Forehead wrinkle are totalled from total RedDot in ForeHead and then the value are scaled between 0-1

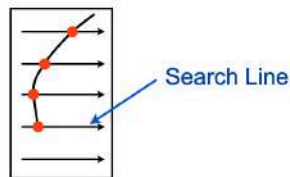


$$FHW = \frac{\text{TotalRedDotInForeHead}}{RD_{maxInForeHead}}$$

## Cheek

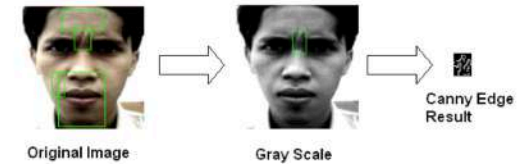


The procedures of counting the Cheek wrinkle are totalled from total RedDot in Cheek and then the value are scaled between 0-1

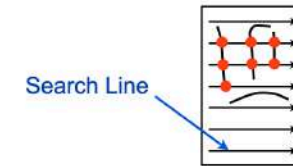


$$CkW = \frac{\text{TotalRedDotInCheek}}{RD_{maxInCheek}}$$

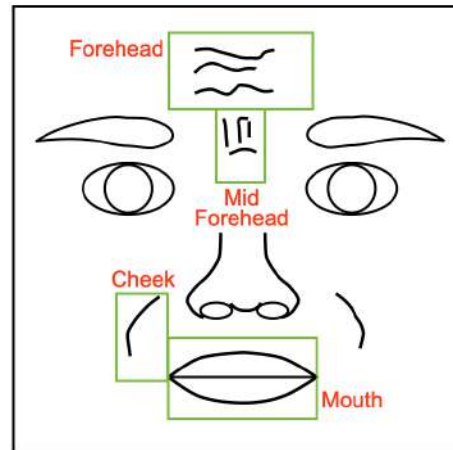
## Mid Forehead



The procedures of counting the MidForehead wrinkle are totalled from total RedDot in MidForeHead and then the value are scaled between 0-1

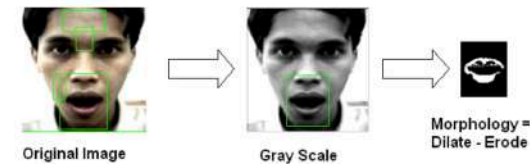


$$MFHW = \frac{\text{TotalRedDotInMidForeHead}}{RD_{maxInMidForeHead}}$$

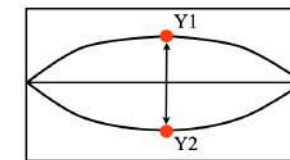


Parts of Facial Feature Extracted

## Mouth



The Mouth value are from mouth height and then the value are scaled 0-1



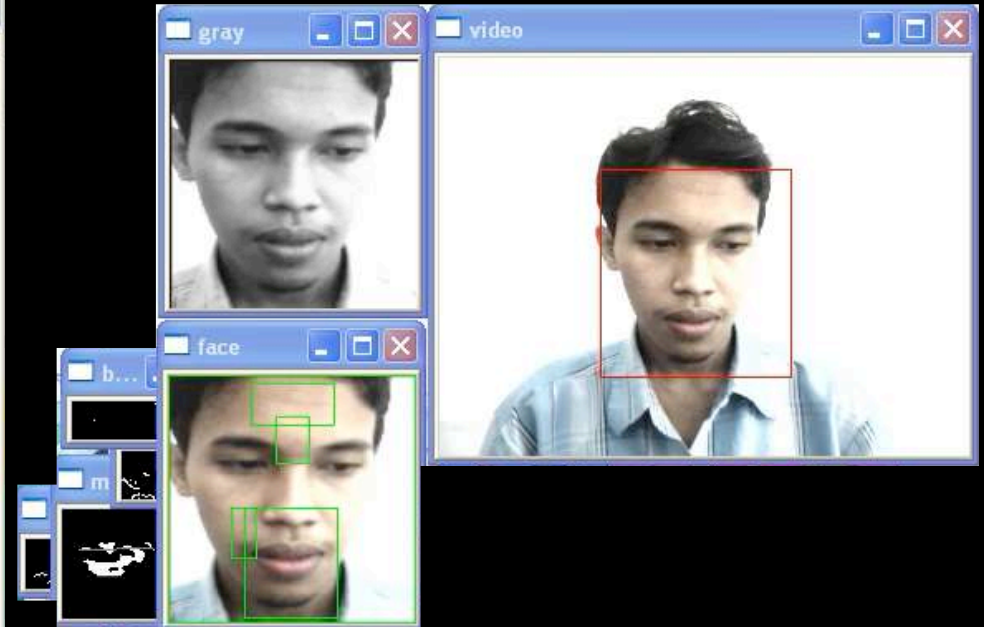
$$V_{MLg} = \frac{(Y2 - Y1)}{V_{MLg}}$$



# Experiment Results

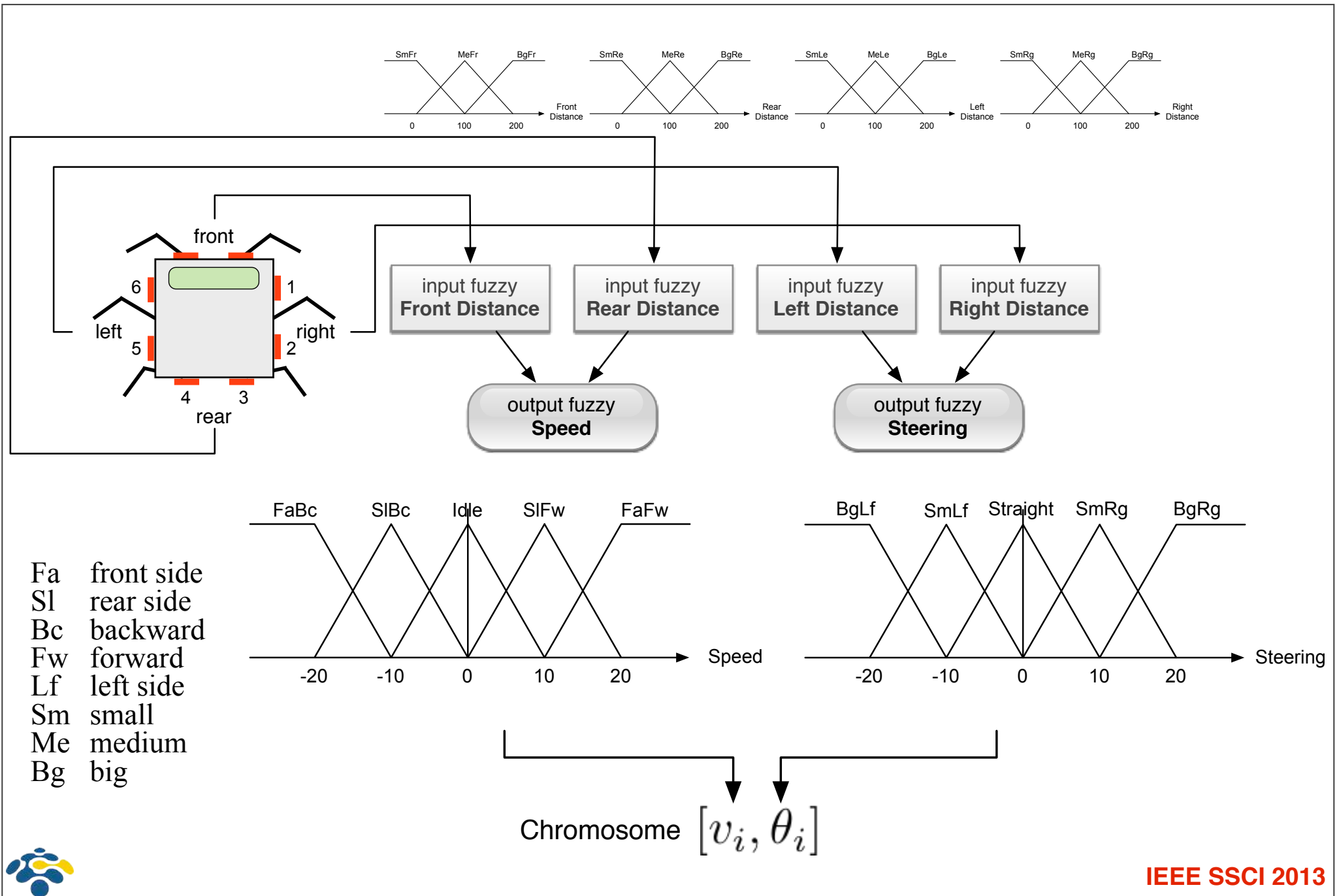
```
c:\Documents and Settings\X@DIZ\My Documents\Visual Studio 2005\Projects\Copy (2) of O... - [ ] X
//////////////////////////////////////////////////////////////// INPUT_ //////////////////////////////////////////////////////////////////////
ForeHead      [ 0.0 percent
MidForeHead   [# 10.1 percent
Mouth         [ 10.1 percent
Cheek         [### 10.1 percent

//////////////////////////////////////////////////////////////// OUTPUT //////////////////////////////////////////////////////////////////////
Anger         [ 10.0 percent
Disgust       [ 11.1 percent
Suprise       [ 10.0 percent
Happy         [# 15.2 percent
Sadness       [ 10.0 percent
Fear          [ 10.0 percent
```





# A Path Planning Behavior Learning of Six Legged Robot Based on Human Teaching Model

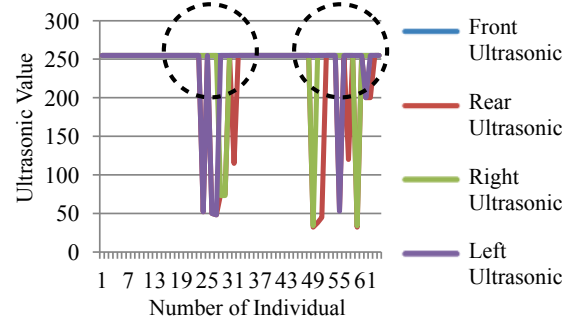


# Experimental Results

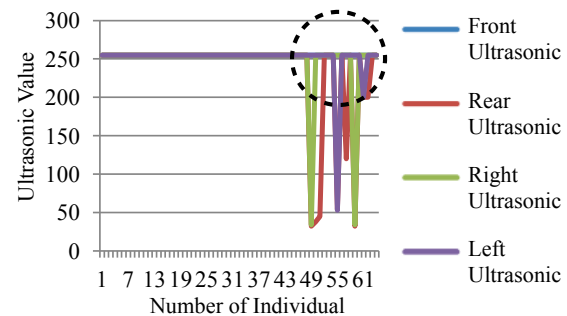
At first, legged robot path planning was trained by human teaching



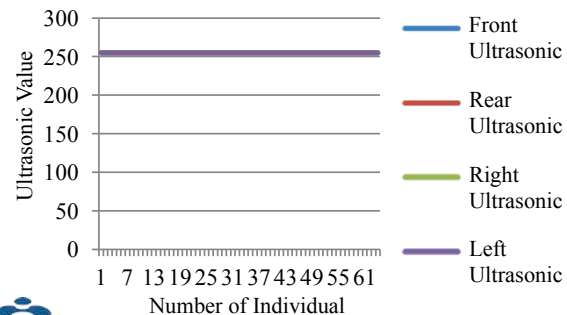
human training



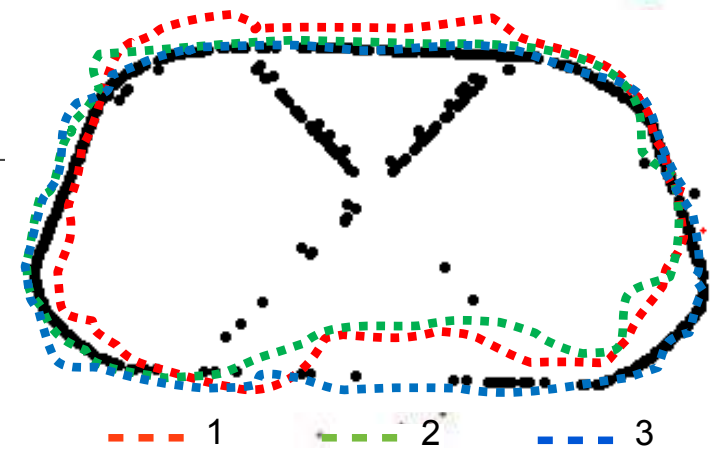
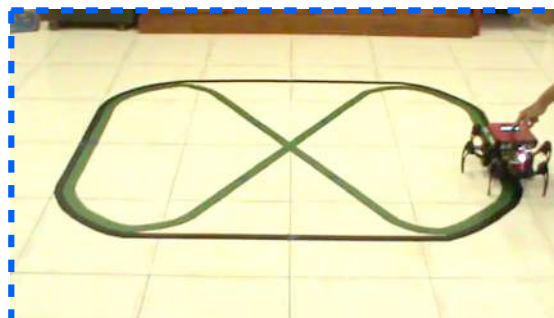
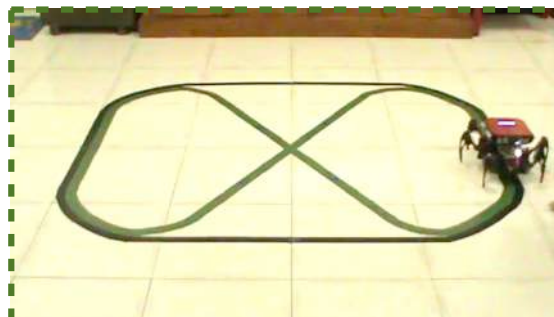
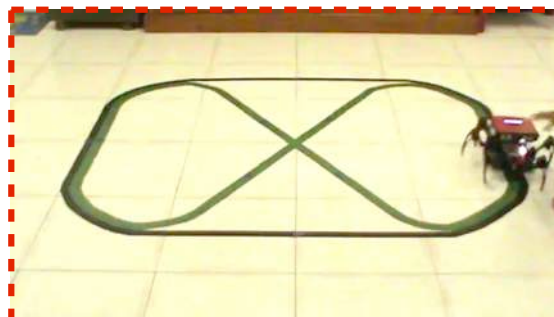
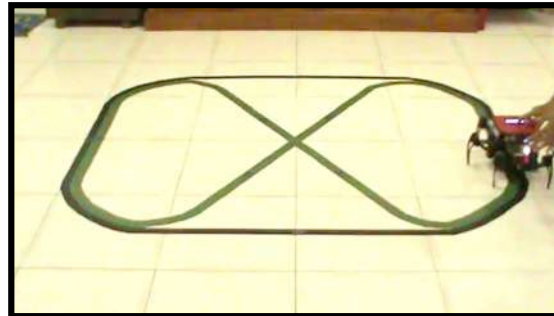
a. The first trial



b. The second trial



c. The third (final) trial



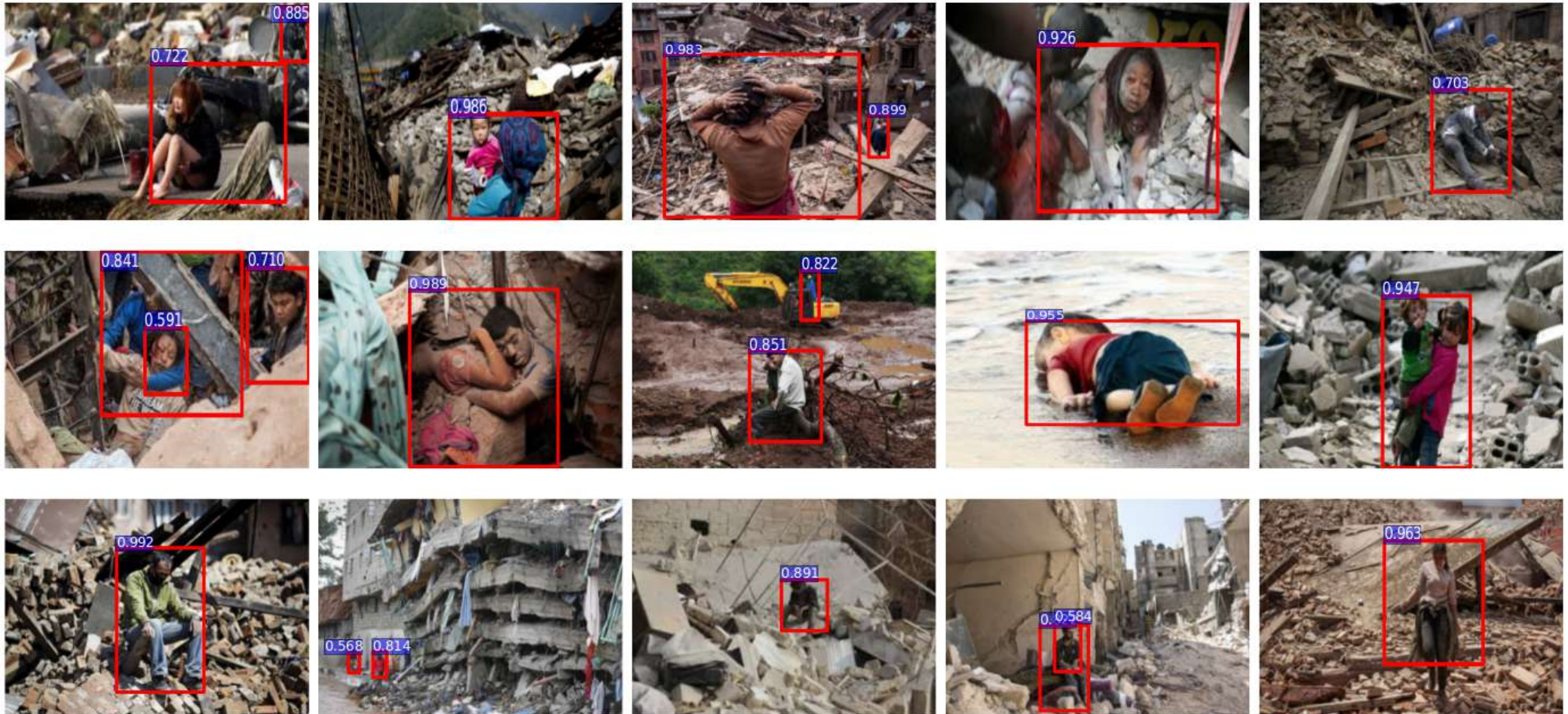
In the first trial, the robot will evaluate its error by using reinforcement learning method led by punishment and reward. In this iteration, the robot will not create a new pattern combination. It means that the Speed and the Steering values are still the same as in the previous iteration. This iteration will then revise the error made by the previous iteration by using reward and punishment value.

The second trial, human teaching for repairing is less required

The third (final) trial doesn't need human training again



# Deep Learning Untuk Mendeteksi Korban Bencana



We release this **Indonesian Disaster Victims (IDV-50)** datasheet.  
The system can work well.



# Simulasi Teknologi Robot Vision

File Edit Add Simulation Tools Plugins Add-ons Scenes Help

Selected objects: 1  
Last selected object name: Peth  
Last selected object type: Peth (bezier curve point count=270, total length=17 7635, p=+0.9415, Vn=+0.1500)  
Last selected object position: x: -1.4500 y: +1.0250 z: +1.7550  
Last selected object orientation: s: +000.00 b: +000.00 g: -000.00  
Simulation time: 00:00:01.64 (dt=50.0 ms)  
Script(s) executed:  
Collision handling enabled  
Distance handling enabled  
Proximity sensor handling enabled  
Vision sensor handling enabled (FBO)  
IK group handling enabled  
Mechanism handling enabled  
Dynamics handling enabled (Bullet)  
Mill handling enabled

Non-threaded: 11 (42 ms), running threads: 0 (0 ms)  
Calculations: 0, detections: 0 (0 ms)  
Calculations: 0, detections: 0 (0 ms)  
Calculations: 1, detections: 0 (18 ms)  
Calculations: 0 (0 ms)  
Calculations: 0 (0 ms)  
Calculation passes: 10 (17 ms)  
Calculations: 0, surface cut: 0 mm<sup>2</sup> (0 ms)

Camera view from drone

Camera view from SAR Station

Simulation paused.  
Simulation resumed.

x=110.167 y=502.167 [0, 0]

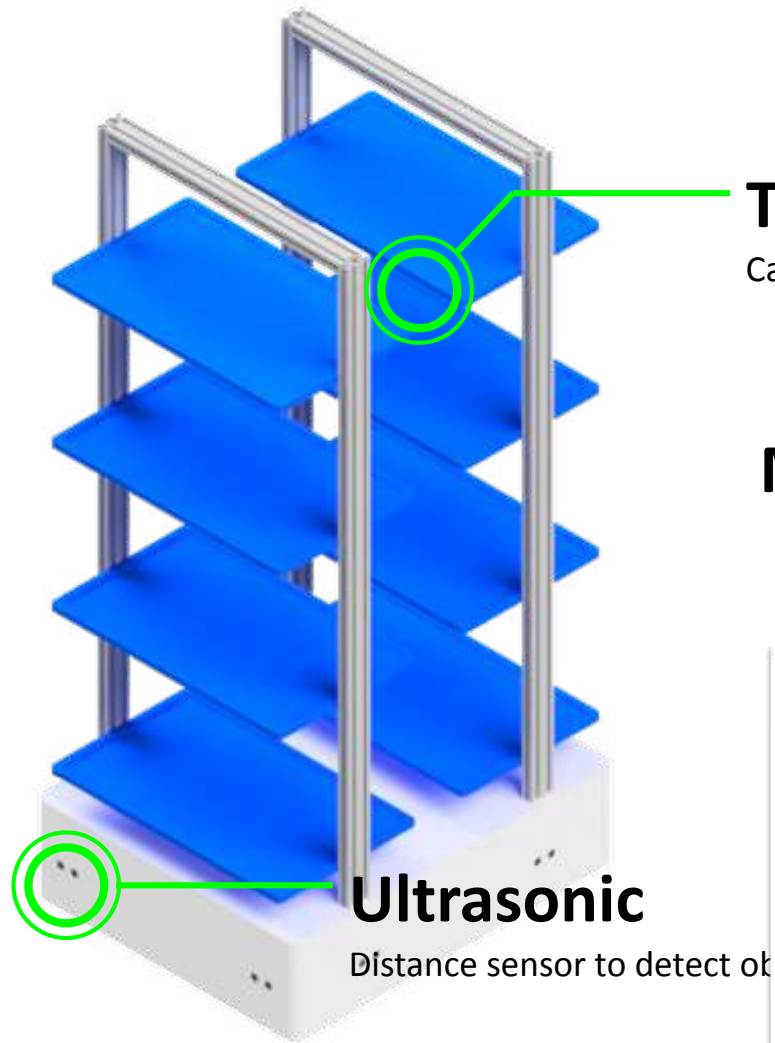
Simulasi teknologi robot vision untuk mendeteksi korban bencana (VREP)





# The Mobile Robot

## Overview



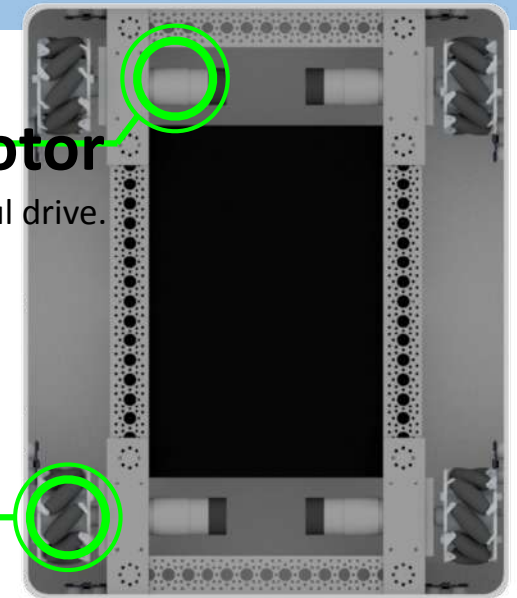
*Isometric View*

### High Torque DC Motor

Providing powerful drive.

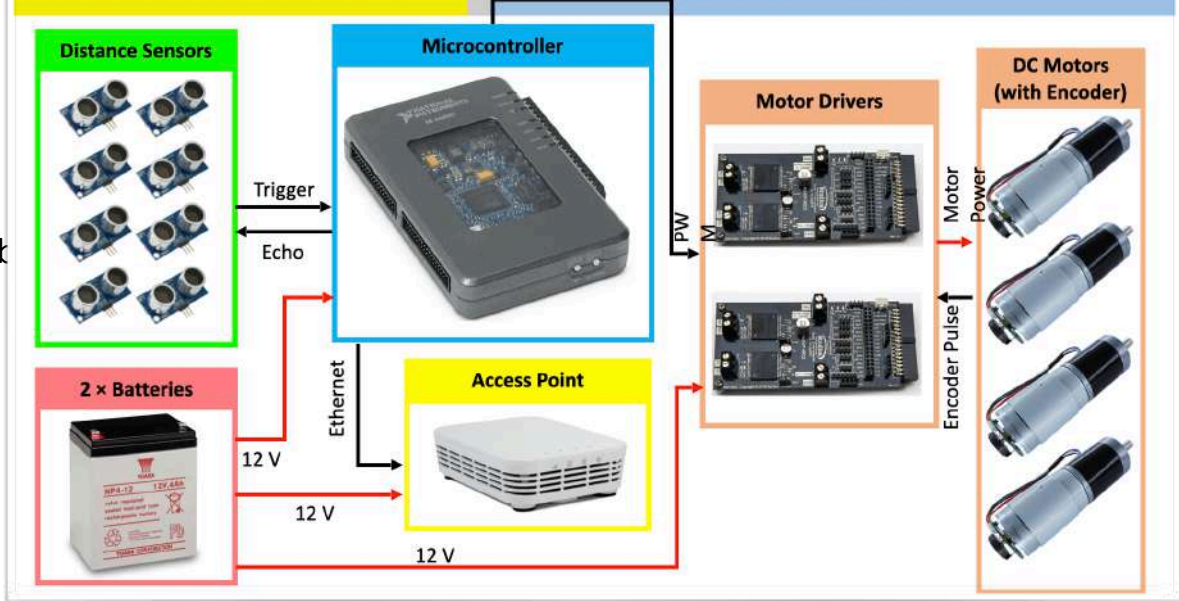
### Mecanum Wheels

Providing holonomic movement and strong hold.



## The Mobile Robot

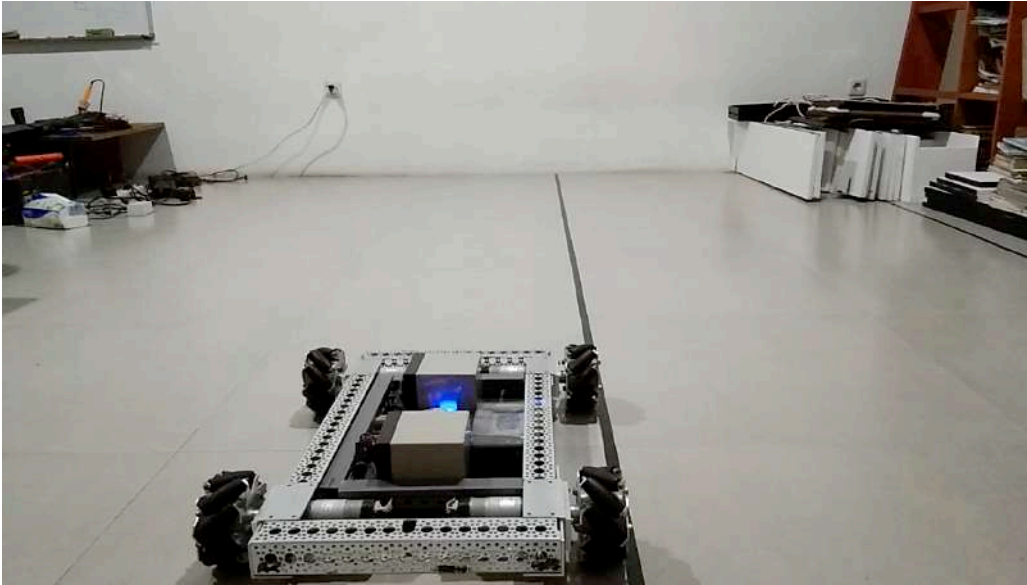
## Electronics System Diagram



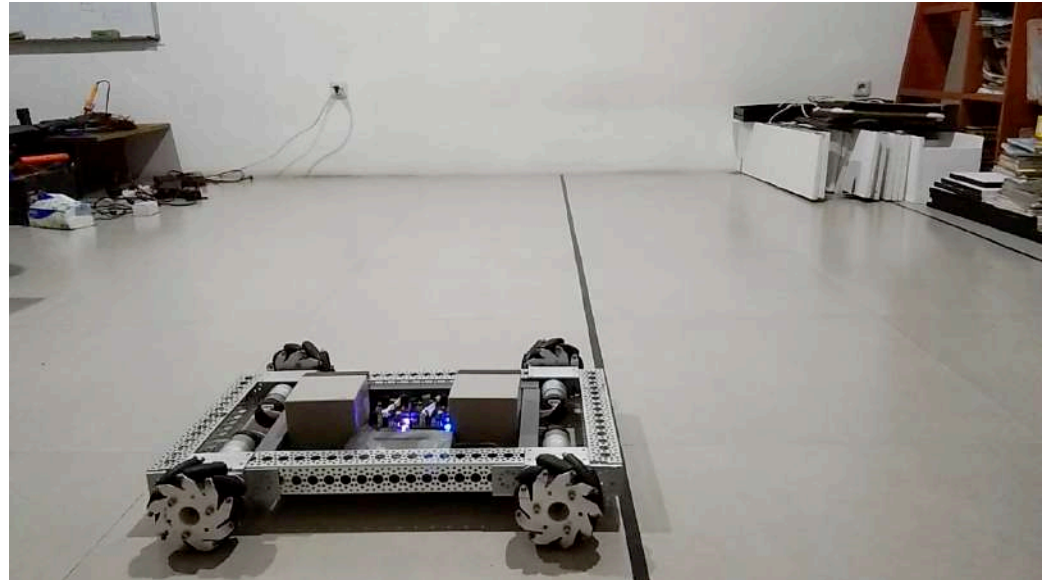
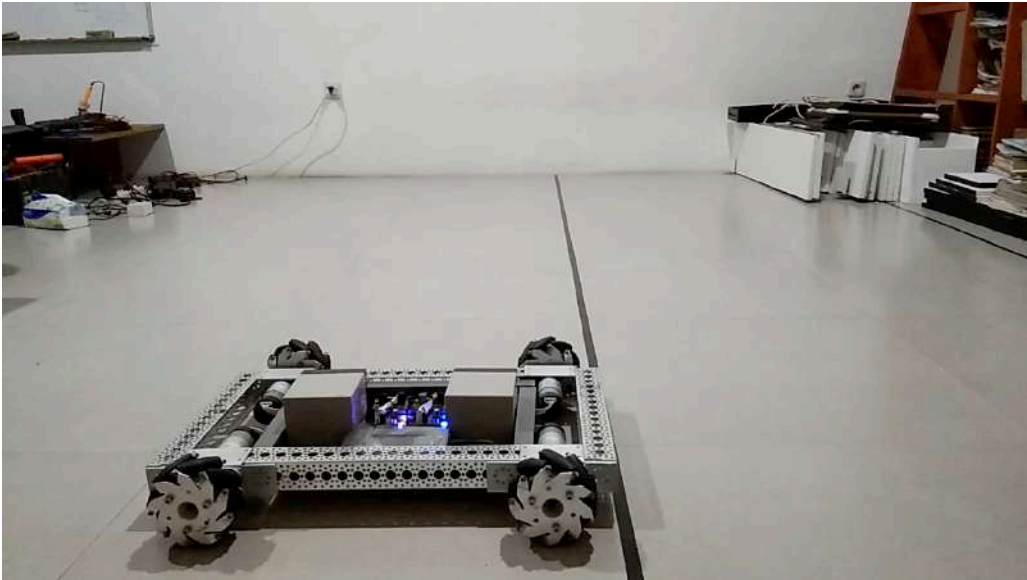
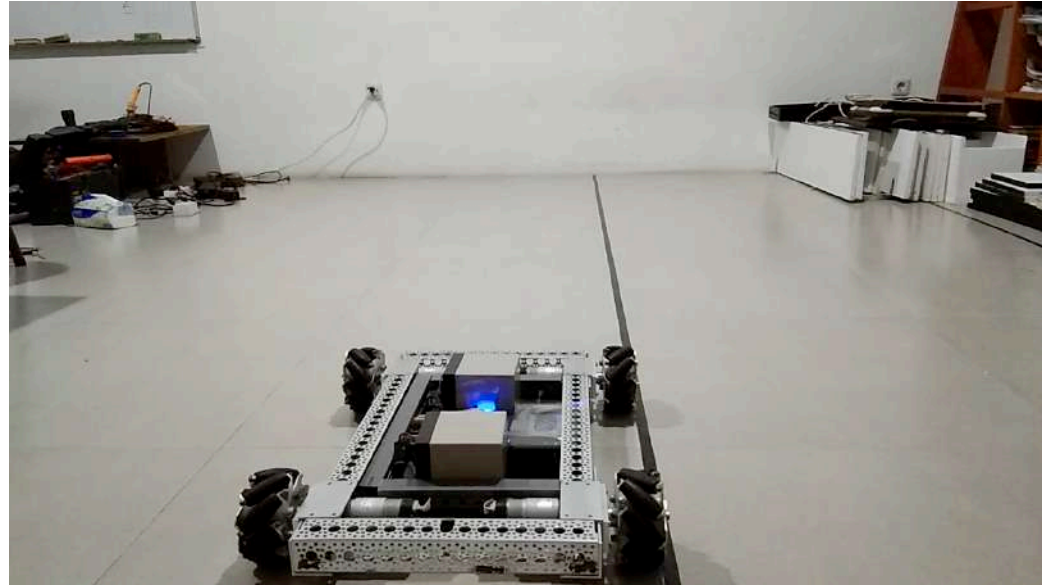
# Progress

## Velocity Control

Open-Loop Motor Velocity Control

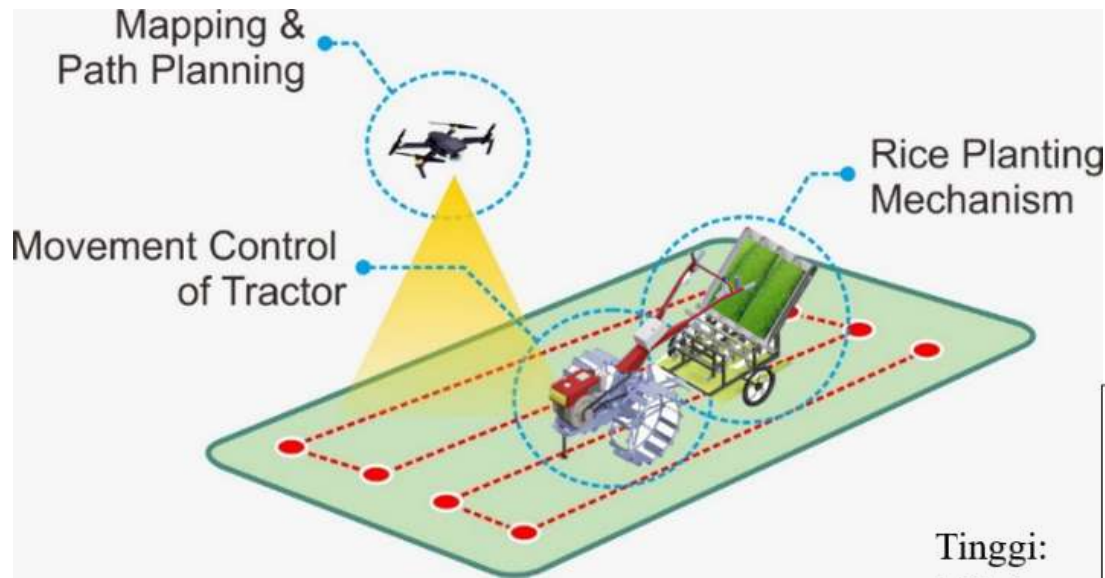


PID Close-Loop Motor Velocity Control

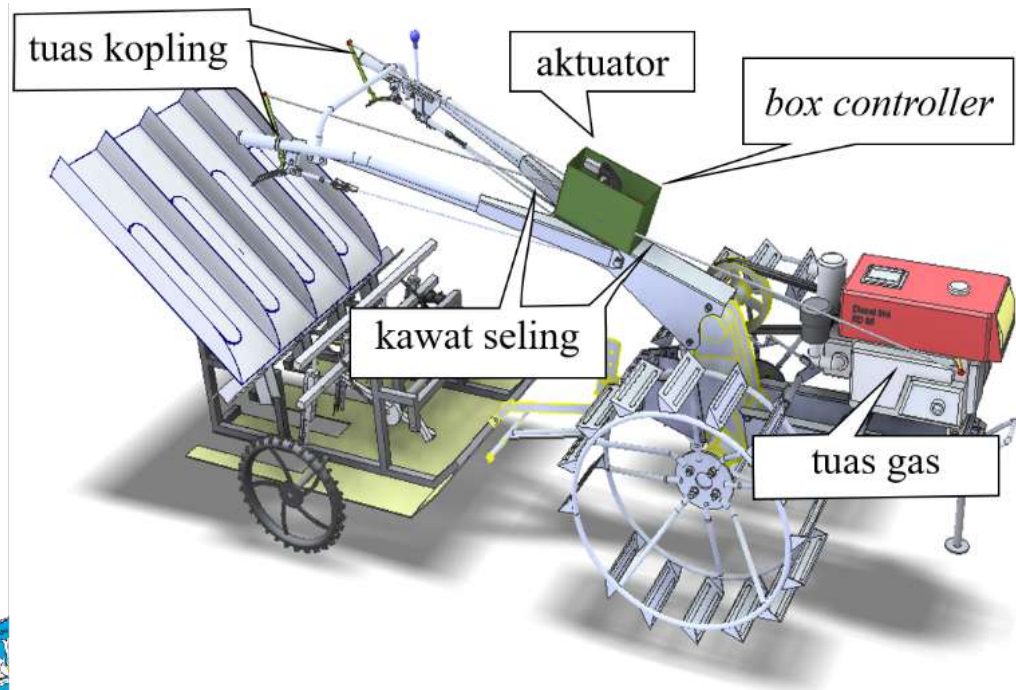
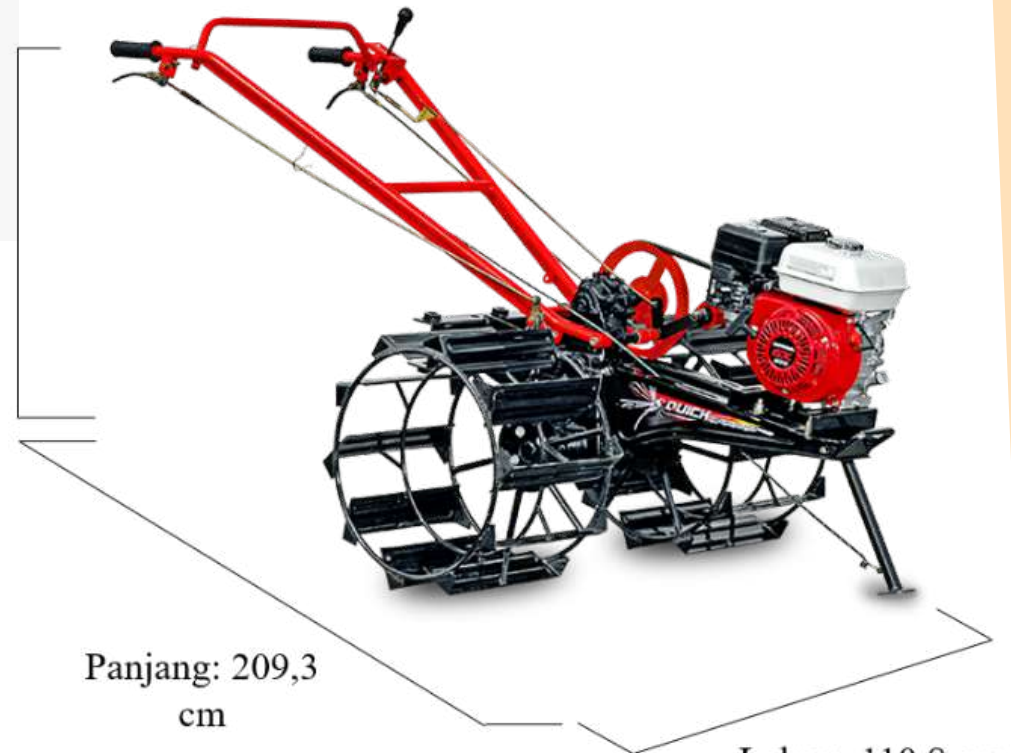




# RoboTani: Agriculture Robot



Tinggi:  
110.5 cm



# RoboTani: Agriculture Robot

video 1:  
**Simulasi Algoritma Trilaterase**

Simulasi Algoritma Trilaterasi

video 2:  
**Simulasi Kendali Mobile Robot dengan Software Processing 2**

Simulasi Kendali Mobile Robot

video 6:  
Pengujian Kendali Sudut Pada Servo Motor

Pengujian Kendali Robot

video 9:  
Pengujian Posisi (Sensor DWM1000)

Pengujian Posisi Sensor

video 8:  
Pengujian Kendali Traktor dengan Comand Serial

Pengujian Kendali Traktor

video 7:  
Pengujian Kecepatan Traktor

Pengujian Kecepatan Traktor

video 10:  
Pengujian Software RemotSoft

Pengujian Software

video 11:  
Pengujian Kendali Low Level dengan Remot Interaktif Remotsoft

Pengujian Kendali Low Level

video 12:  
Pengujian Kendali Arah Hadap

Pengujian Kendali Arah Hadap



# 8 Keterampilan Paling Dicari Setelah Pandemi

## 1. Adaptability and Flexibility

Someone that is going to succeed in a post-coronavirus-world will need to be able to adapt to ever-evolving workplaces and have the ability to continuously update and refresh their skills.



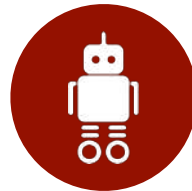
## 5. Critical Thinking

Able to think critically.  
Which ones suitable or not.  
Which ones fact and hoaxes.



## 2. Tech Savviness

Technologies such as artificial intelligence, big data, the Internet of Things, virtual and augmented reality, and robotics will make businesses more resilient to future pandemics, and anyone that can help companies exploit these technologies will be in a great position.



## 6. Digital And Coding Skills

People who can keep the digital business running—and thriving—during economic downturns or pandemics that make in-person business impossible or less efficient are going to be on the must-hire list.



## 3. Creativity and Innovation

We will need human ingenuity to invent, dream up new products and ways of working. Human creativity is going to be essential.



## 7. Leadership

Professionals with strong skills in leadership, including how to bring out the best and inspire teams as well as encourage collaboration, will be in demand.



## 4. Data Literacy

With the right data, companies are able to better predict the impact of future business disruptions and are better able to serve customers with the right products and services during or after any pandemic. Companies that understand business trends and shifting customer needs are better able to respond in the right way.



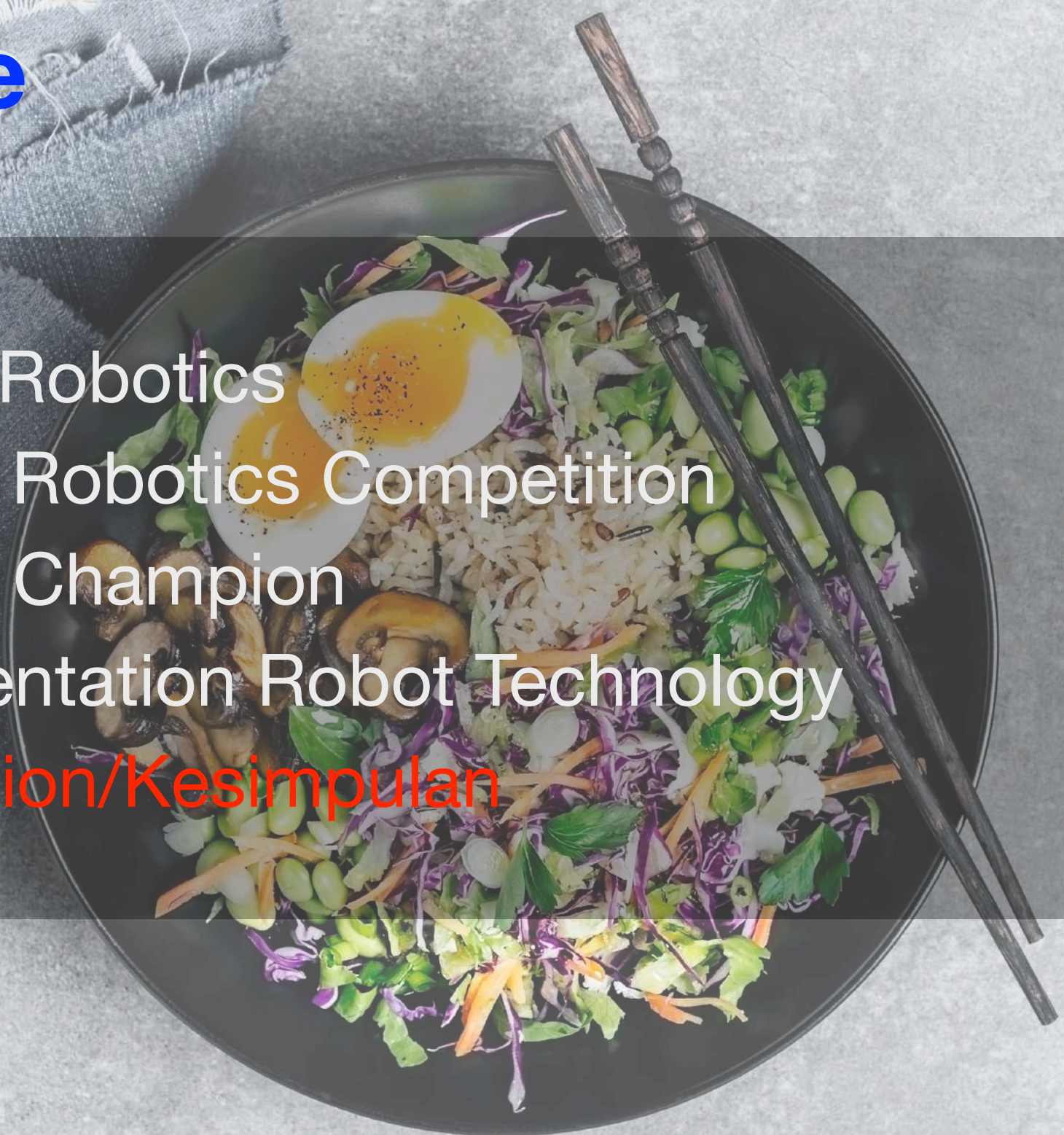
## 8. Emotional Intelligence

The ability to be aware of, express, and control our emotions and be aware of others' emotions is what emotional intelligence is all about.



# Outline

- What is Robotics
- (Mobile) Robotics Competition
- Road to Champion
- Implementation Robot Technology
- Conclusion/Kesimpulan





# Kesimpulan

- Pemusatan latihan atau Training Center (TC) bertujuan salah satunya membangun mobile robotics dan melakukan penelitian untuk mencari metode yang paling efektif dan efisien dalam menyelesaikan tujuan serta menyiapkan lingkungan yang kondusif sesuai dengan kriteria kompetisi internasional.
- Robotics merupakan multidisiplin ilmu dari beberapa cabang ilmu, antara lain mekanik, elektronik, embedded system, logic programming dan control.
- Untuk menjadi juara, selain pendanaan diperlukan kerja keras, kerja yang kompak, suasana yang menunjang, dan mental yang kuat.
- Untuk dapat mewujudkan robot yang dapat diimplementasikan dalam dunia riil, TKT (tingkat kesiapan teknologi) dapat dicapai melalui jam kerja dan pengalaman.



# Silakan Bergabung

Sehat, Sukses dan Barokah selalu

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Websites: [www.pens.ac.id](http://www.pens.ac.id)

Sabda dari Nabi Muhammad SAW

***Khoirunnas anfa'uhum linnas***

**Sebaik-baik manusia adalah yang paling banyak memberikan manfaat kepada sesama manusia.**

